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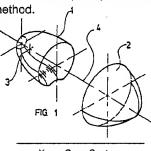
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- Vehicular headlight and method of producing an optically effective system of same.
- (5) A vehicular headlight, in particular an automobile headlight, including a reflector (1) having a reflecting surface, is capable of illuminating a flat target surface to be illuminated with a desired light distribution by optimal utilization of the light source of the headlight. Therefore the optically effective surface of the headlight is characterized by point asymmetry in substantially all planes cutting said reflecting surface. This can be realized by using a method for producing said optical surface comprising the steps of:

mathematically representing said surface by creating a spline from bivariate tensor product of polynomials; deriving mathematical data in computer input format from said mathematical representation; and inputting said data to a computer for controlling an apparatus by which the mathematical representation of said optical surface is reproduced in physical form.

Such splines, in turn, are represented and subsequently altered, preferably either by the so-called Bezier method or by the so-called Basis-spline method.



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### Vehicular Headlight And Method of Producing An Optically Effective System of Same

The invention relates to a vehicular headlight in particular an automobile headlight, capable of projecting on a flat target surface a predetermined illumination pattern, said head-light including a reflector having a reflecting surface.

Due to legal regulations directed to traffic safety, some known automobile headlights are provided with a masking element arranged in the beam of light between the reflector and a distributor lens in order to meet specific requirements with respect to illumination range, color uniformity, the illumination pattern on the roadway and its marginal area, and light/dark delimitation criteria.

The use of such masking elements, however, is one of the main reasons why such headlights mentioned can neither produce their full light output, nor are they free from the occurrence of color fringes, which runs counter to the requirement for emitting a uniformly colored light.

An automobile headlight is known from DE-AS 18 02 113 by means of which a sharp light/dark delimitation (low beam head-lights) is to be achieved without the use of a masking element. For this purpose, the reflector comprises two narrow, axially symmetrical sectors forming the main mirror surface regions which effect the sharp light/dark delimitation. Two parabolic additional mirror surfaces supplement these surfaces. Thus, the known reflector consists of four individual surfaces adjoining at four boundary edges. Such boundary edges cause the reflected light to form irregular light beams directed at the surface to be illuminated, so that a continuous, i.e. smooth, light distribution of high intensity is impossible.

A reflector known from DE-OS 33 41 773 shows a similar structure. Also in this case, the object of distributing the light rays reflected by the reflector in their entirety below the light/dark delimitation, is attained incompletely and discontinuously. The known reflector also consists of two parabolic sectors which are arranged symmetrically around its horizontal axis and to which adjoin two pairs of so-called deflecting surfaces. Instead of four surfaces known from the reflector according to DE-AS 18 02 113, the reflector of DE-OS 33 41 773 comprises six surfaces which adjoin at six boundary edges and which, however, do not substantially improve the disadvantages of discontinuity of light distribution, even though the adjoining boundary edges of the individual reflector surfaces allegedly do not show discontinuities.

It is the object of the invention to provide a headlight that illuminates a surface to be illuminated with a desired light distribution by optimal utilization of the light source of the headlight, particularly under the consideration of the legal regulations in several countries.

The above object is attained by providing the headlight with an optically effective surface which is characterized by point asymmetry in substantially all planes cutting said reflecting surface.

The optically effective system may be represented by the reflector surface itself.

The optically effective system may also be represented by the surface of an optical element arranged in the light beam reflected by the reflector surface.

The optically effective system may also be a combination of the reflector surface and a surface of the optical element in the light beam reflected by the reflector surface.

The surface or surfaces of the optically effective system according to the invention satisfy the following single mathematical formula:

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$$X = \frac{\frac{\text{rho}^2}{\text{R (phi)}}}{1 + \sqrt{1 - (K(\text{phi}) + 1) \cdot \frac{\text{rho}^2}{R(\text{phi})}}} + \frac{\text{n=ne}}{\text{n=0}} AK_n(\text{phi}) \cdot \text{rho}^n,$$

wherein

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wherein
$$R(phi) = \frac{m = me}{\sqrt{\frac{/}{m = 0}}} [Rc_m \cdot cos(m \cdot phi) + Rs_m \cdot sin(m \cdot phi)],$$

$$K(phi) = \frac{\underline{i} = \underline{ie}}{\underbrace{/}} [Kc_{\underline{i}} \cdot cos(\underline{i} \cdot phi) + Ks_{\underline{i}} \cdot sin(\underline{i} \cdot phi)],$$
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$$AK_{n}(phi) = \frac{k = ke}{\frac{k}{k}} [AKc_{nk} \cdot cos(k \cdot phi) + AKs_{nk} \cdot sin(k \cdot phi)]$$

and wherein

X represents a linear cylindrical coordinate of the headlight axis, which extends substantially in the direction of the light beam produced by the optically effective surface,

rho is the radius vector of said cylindrical coordinates,

phi represents the polar angle of said cylindrical coordinates of the loci,

n represents integers from 0 through 50, preferably through 10,

m, i and k represents integers from 0 through at least 3, preferably through 20,

R(phi) represents a coefficient which depends on phi and defines the limit value of the radii of curvature of the conic part of the surface at the apex with axial planes extending through the headlight axis when X = 0.

K(phi) represents a conic section coefficient as a function of phi,

 $AK_n(phi)$  represents one of ne+1 different aspheric coefficients as a function of phi,

Rcm and Rsm each represent one of me + 1, and

Kc, and Ks, each represent one of ie + 1 different constant parameters,

AKc<sub>nk</sub> and AKs<sub>nk</sub> and each represent one of (ne + 1) (ke + 1) different constant parameters.

The above optical surface formula is a variation of a known formula for a surface of rotation having coefficients R, K, AKn which are independent of phi. In this known formula, each value of X produces a certain value of rho which is thus independent of phi. Due to the dependency of the above coefficients on phi in this representation, each value of X produces a value of rho which is dependent on phi. Thus, the radius vector rho is not only a function of X, as is the case in the known formula, but-also a function of phi. The designations for K and AKn as "conic section coefficients" and "aspheric coefficients", respectively, result from the known formula which contains the coefficients independent of phi. In connection with the known surfaces of rotation, the designation "basic radius" for R is also commonly used.

The optically effective system of a headlight according to the above formula can be calculated in that for me and ie, preferably 20, values of each of the parameters  $Rc_m$ ,  $Rs_m$ ,  $Kc_i$  and  $Ks_i$  and for (ne + 1) (ke + 1) values of the parameters  $AKc_{nk}$  and  $AKs_{nk}$ , wherein preferably ne = 10 and ke = 20, the radius of curvature coefficient R(phi), the conic section coefficient K(phi), and the aspheric coefficients  $AK_n(phi)$  are determined.

Because of the mutual dependency of the coefficients in the foregoing optical surface formula, mathematical manipulation of the representation of one particular region of the surface representation causes changes in other regions of the representation, which makes the overall mathematical process of arriving at desired surface representation very complex and time-consuming. Accordingly, a preferred

method according to the invention for mathematically producing the desired optical surface includes the step of mathematically representing an approximation of that surface with mathematically represented surface segments in a manner that allows individual segments to be mathematically manipulated without influencing the optical properties of other regions of the representation. Preferably, such a manner of mathematical representation uses bivariate tensor product splines. Such splines, in turn, are represented and subsequently altered, preferably either by the so-called Bezier method or by the so-called B-spline method, starting with the determination of initial bivariate polynomials which describe surface segments and are equal at the common sides of adjacent surface segments through the second derivative (continuity at the common sides of the segments).

This can be realized by the determination of initial bivariate polynomials which describe surface segments of an approximate surface to a known optical surface, e.g. a paraboloid.

in a preferred realization of this method initial bivariate polynomials are determined describing initial surface segments having desired optical properties only of an initial region of the optically effective surface. Subsequent further bivariate polynomials are determined describing further initial surface segments located adjacent to the initial region until an approximate surface to the desired optically effective surface is achieved.

In both of said realizations, said approximate surfaces are, step by step, locally changed by varying the coefficients of the bivariate polynomials while retaining said continuity through the second derivatives without influencing optical properties of other regions of said approximate surface until the resulting representation of said optical surface achieves the desired optical properties.

Regardless of the method used to devise the mathematical representation of the desired optical surface in accordance with the invention, the resulting representation is then expressed in computer language and is used as the input to a computer that controls a machine tool to reproduce the mathematical surface representation in physical form.

Due to the asymmetry of the plurality of sections intersecting the reflector and/or the optical element, each reflective spot of the reflector illuminates a definite area on the surface to be illuminated, but a region of the illuminated surface may be illuminated from more than one reflector spot, i.e., the shape of the reflector has been calculated and determined such that the light rays reflected by the reflective spots of the reflector distribute the available amount of light on the surface to be illuminated according to the brightness desired at the various spots so that an undesired brightness increase or decrease is avoided and optimal utilization of the available light source is achieved.

Consequently, light losses caused when the light beam is formed by means of the optically effective surface according to the invention are minimal, and the amount of light emitted by the light source can be fully utilized.

In addition, an improved lateral field illumination as well as a gradual, instead of an abrupt, light/dark delimination is achieved, which is desired with respect to road traffic safety. Furthermore, it is not necessary to dissipate heat developed at a masking element due to direct and indirect irradiation.

Generally, a reflective filter layer can be used expediently for heat removal from the reflector, particularly a reflector made of plastic material.

Similarly, a lens or other optical element in the light path from the reflector can be protected by a reflective filter layer on the reflector itself and/or by a cold mirror, preferably arranged at an inclined angle in front of the reflector opening. If, for example, such a cold mirror is arranged in front of the reflector at an angle of 45 degrees, the optical axis of the light beam reflected by the mirror surface will extend normal to the axis of the reflector so that an L-shaped configuration of the headlight is obtained, which fact considerably reduces the space required for installing such a system, such reduction is advantageous in an automobile. The optical means interposed in the light beam reflected by the cold mirror surface is then transilluminated only by the cold light and, as a result, can be manufactured of thermosensitive material. In this case, the axis of the headlight forms a right angle, the legs of which are the reflector axis and the optical axis of the optical element arranged in front of the reflector.

Because the headlight according to the invention does not require any of the usual diffusion screens, the automobile body designer is substantially free in shaping the headlight front glass.

A lens arranged in front of the reflector opening can either consist of a colored material or can be provided with a color filter coating to meet local requirements for coloring the light emitted by the reflector.

Surprisingly, tests conducted have shown that the optically effective surface according to the invention produces not only an optimal low beam light, but also creates an excellent high beam when using a double-filament lamp, especially because the high beam is not impaired by a masking element.

In summary, a headlight designed according to the invention avoids the use of masking elements and provides optimal utilization of the available light, achieves the desired light distribution with a considerable

increase in total light output, and avoids the occurrence of color fringes.

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Two embodiments of a headlight and the methods according to the invention will now be described with reference to the drawing and the accompanying tables.

Fig. 1 shows a perspective view of a first embodiment of a headlight consisting of a reflector and a lens,

Fig. 2 is a schematic perspective view of a cross-section (normal to the headlight axis) of the optically effective surface of a headlight within the coordinate system, X, Y and Z, showing cylindrical coordinates X, rho and phi, for the illustration of the first and second embodiments.

Figs. 3a, 3b are a schematic representation of two of many possible examples for the illumination of a surface to be illuminated which can be achieved when using the headlight according to the invention,

Fig. 4 is a projection, parallel to the headlight axis "X", onto a plane normal to the X axis, of the optically effective surface of the headlight divided up into surface segments,

Fig. 5 shows an enlarged representation of one surface segment according to Fig. 4, and

Fig. 6 shows the optical path of the light rays between the optically effective surface according to Fig. 1 and a surface to be illuminated.

Table I shows the parameters for calculating the reflector surface by means of the above-mentioned formula,

Table II shows the parameters for calculating the surfaces of a lens arranged in front of the reflector which lens, together with the reflector surface, forms the optically effective system of a first embodiment of the headlight, by means of the abovementioned formula,

Tables III and IV show the coefficients (b) of the bivariate polynomials for defining the surface segments of the optically effective surface formed of the reflector surface and a lens surface according to the first embodiment.

Table V Shows the "b" coefficients of the Basis-Spline-Method for defining the optically effective surface of the second embodiment of the headlight.

As shown in Fig. 1, the optically effective surface of the headlight according to a first embodiment of the invention is designed asymmetrically on a reflector 1. A lens 2 is arranged coaxially to the headlight axis 4. Reference numeral 3 designates a light source arranged within the reflector (e.g., a double filament lamp). The arrangement of the above-mentioned components on the headlight axis 4 represents one of several possible embodiments.

In addition to the surface of reflector 1, it is possible to form at least one surface of lens 2 such that one surface is characterized by point asymmetry in all planes cutting said surface, which is a part of the optically effective surface.

Moreover, lens 2 may be arranged in an offset and/or tilted relation to the headlight axis 4 to effect light emission in one or several directions other than the main direction of emission.

The glass or plastic lens 2 itself can also be used for sealing the front of the headlight. In this case, a separate front glass having an optically effective surface pattern is not required. For this purpose, at least the outer surface of the lens is scratch-resistant. Instead of the lens being used as a headlight component, a planar plate can be inserted, e.g. in the second embodiment.

For an intense light emission a double-filament lamp is provided as light source 3 so that the headlight can be used in the low and high beam mode.

The reflector surface and/or the optically effective lens surface can be described by means of the formula given in the introduction to the description.

The 12  $\times$  21 = 252 parameters Rc<sub>m</sub>, Rs<sub>m</sub>, Kc<sub>i</sub>, Ks<sub>i</sub>, AKc<sub>nk</sub> and AKs<sub>nk</sub> of a reflector surface satisfying the mentioned formula are given in Table I, Pages 1 to 3. Together with a lens which is placed in front of the reflector and the two surfaces of which are defined by the parameters given in Table II, the reflector surface forms the optically effective surface of a first embodiment of the headlight according to the invention.

The addition of E-02 or E+02 at the end of the numerical values given in Tables I and II means that such values must be multiplied by  $10^{-2}$  or  $10^{+2}$  respectively.

The values given in Table II indicate that the first lens surface has an infinitely large radius of curvature and thus represents a plane. As the second lens surface is defined only by the parameter values for me = ie = ke = 0, said surface represents a surface of rotation about the headlight axis.

Using the above-described embodiment of a headlight an illumination of the surface to be illuminated will be achieved as stated in Fig. 3b in a schematically simplified form.

An initial surface used in performing the first step of a first method is based on an optically effective surface of a known shape, e.g., a paraboloid of revolution. By calculation, the initial surface is divided up into 100 initial surface segments 5' (Fig. 6), the projections of which, indicated on a plane arranged normal to the headlight axis X, are designated with the reference numeral 5 (Figs. 4 and 5). For the purpose of

simplification, the projections 5 are represented by only 25 surface segments 5' (Fig. 4).

Such sub-division results from the fact that the initial surface is dissected by means of two families of parallel planes, the planes of one of the families extending normal to the planes of the other family and the planes of both families extending parallel to the headlight axis.

With the initial surface segments 5' having thus been calculated, the corners can now be determined. In Figs. 4 and 6, the Cartesian coordinates X, Y and Z of the headlight are represented, the X-axis defining the headlight axis. The X-coordinates of the corners  $b_{00}$ ,  $b_{00}$ ,  $b_{00}$  and  $b_{00}$  of each surface segment 5' are inserted in the following bivariate polynomial as corner coefficients:

wherein "y" and "z" (Fig. 5) in contrast to "X" and "Z" (Fig. 4), are Cartesian coordinates starting from corners 6 (Fig. 5) of each surface segment having the "X" coordinate "b₀".

If the Bezier method is used, the remaining coefficients of the bivariate polynomials of each surface segment, are then calculated according to this method such that the polynomials are identical in the lines of contact of adjacent surface segments through the second derivatives. The Bezier method is disclosed, for example, in W. Boehm, Gose, Einfuehrung in die Methoden der Numerischen Mathematik, Vieweg Verlag, Braunschweig, 1977, Pages 108-119. The bivariate polynomials thus calculated result in surface segments which are approximations to the initial surface segments. If then the corner coefficients of the polynomials of surface segments are varied at desired loci of the optically effective surface and subsequently, as described above, the remaining coefficients are calculated, a local change of the shape of the surface described by the polynomials will be possible, without changing other regions of that surface.

In order to obtain an optically effective surface having the desired properties, the corner coefficients of the polynomials and subsequently the remaining coefficients are step by step changed such that the desired light distribution is achieved, which can be checked each time a change has been made. This procedure is continued until the resulting mathematical surface representation achieves the desired optical properties.

The larger the number of the surface segments 5′, the more the desired light distribution on the surface to be illuminated is achieved. The same applies to the degree of the bivariate polynomials, that's to say the higher the degree of the polynomials, the more the desired light distribution on the surface to be illuminated is achieved.

Proceeding from corner 6, each projection 5 of a surface segment 5' extends in "y" and "z" directions by the standardized unit of 0 to 1. In the embodiment, this unit is characterized by a polynomial having sixteen b coefficients ( $b_{00}$  through  $b_{33}$ ). For each surface segment the values for "y" and "z" are inserted in the polynomial and the coordinate "X" is calculated. The projections 5 of the surface segments 5' may be square or rectangular. The corners 6 of adjacent surface segments must, however, coincide in order to obtain the desired continuity at the contacting lines of adjacent surface segments and thus a continuity of the total reflector surface.

Fig. 5 shows an enlarged representation of a projection 5 of a surface segment 5' of the surface of reflector 1. Part of the surface segment 5' directs a light beam to the surface 7 to be illuminated (Fig. 6). In this connection, the shape of the projected image is defined by the part of the surface segment 5' forming a curve in the Y and Z directions. Depending on the required shape of the surface 7 to be illuminated, the individual adjacent surface segments are oriented such that each surface segment 5' corresponds to an area 8 on surface 7. If desired, areas 8 of different surface segments 5' may overlap or even coincide. The distribution of the amount of light on the surface 7 to be illuminated is not limited to uniformly distributing light across the total surface but, if desired, the light intensity may vary continuously across the surface to be illuminated.

In Tables III, Pages 1 through 20, and IV the "b" coefficients of the surface segments of the first embodiment of a headlight are given, said segments being described by the above-mentioned formula of bivariate polynomials. The surface segments are designated "segments RS" in the above tables, with R and S representing the lines and columns, respectively, shown in Fig. 4.

The surface segments given in Table III form the reflector surface and the values given in Table IV define the two surfaces of a lens which is arranged in front of the reflector and, together with the reflector surface, forms the optically effective surface of the headlight effecting the illumination of the surface to be illuminated given approximately in Fig. 3b.

As will be apparent from Table IV, in this embodiment, too, the first lens surface is a plane. It follows from the values b = 0 that for all loci of all surface segments, X will always be 0.

A headlight in compliance with the values given in Tables I and II or III and IV is designed such that the distance between the planar surface of lens 2 which is arranged coaxially to the axis of reflector 1 and the apex of the reflector amounts to 118 millimeters.

The preferred method for representing and manipulating the coefficients of the bivariate polynominals of the segments representing an optically effective surface for the headlight uses the Basis-spline Method according to De Boor (see "A PRACTICAL GUIDE TO SPLINES", Applied Mathematical Sciences, Volume 27, Springer Verlag Berlin, Heidelberg, New York).

According to this method, as in the previously described method, first bivariate polynomials are determined describing initial surface segments having desired optical properties of a region of the optically effective surface and beginning with this initial region, further bivariate polynomials are determined located adjacent to said region, until an approximate surface to said optical surface is achieved.

The achieved approximate surface is then changed locally by varying coefficients of said Basis splines while retaining continuity through the second derivatives within the varied region, without influencing optical properties of other regions of said approximate surface. Continuing in this manner the approximate surface is varied until the resulting representation of said optical surface achieves desired optical properties.

In this B-spline method for representing the optical surface, the X-range of 0 to 67 mm and phi-range of 0 to 360 degrees are divided into sub-intervals by means of partition points. Knot sequences for said ranges and sub-intervals are chosen so that fourth order B-splines in the respective variables are continuous through the second derivative. The B-splines in the X variable satisfy "not-a-knot" end conditions. The B-splines in the phi variable satisfy periodic end conditions. Within the range of the variables, division points and knot sequences the resulting B-spline sequences will be denoted by  $B_k(x)$ , k=1 to 15, and  $P_j(phi)$ , j=1 to 15. Said reflector surface is then represented by means of the expression

rho = 
$$\frac{15}{k=1}$$
  $\frac{15}{k=1}$   $b_{kj}B_k(x)P_j(phi)$ 

where rho is the radius of said reflector surface at position x along the cylindrical coordinate (X-axis) axis and at angle phi with respect to the z-axis.

The Table V shows the coefficients  $[b_{kj}]$  and knot sequences for the x variable and phi variable of a second embodiment. These data are sufficient input data for a computer to calculate a reflector surface having the desired properties when a light source lamp of known characteristics is used, e.g., a halogen H4 lamp. Referring to Fig. 2, said light source should be positioned so that the axis of its low beam filament is coincident with the x-axis with the end of the filament closest to the base located at x=29 mm. Said lamp should be oriented so that its reference pin is at angle 75° as measured from the x-axis according to the diagram in Fig. 2. The H4 lamp has three pins to orient the lamp in a housing, one of them being the reference pin.

The data indicated in the Tables I to V are generated by a computer, for instance of the type Micro-Vax 2000 using the FORTRAN language. In a subsequent step these data, representing a net of X, Y and Z coordinates, are transferred to a CAD (Computer Aided Design) Anvil programm as generated by the Manufacturing Consulting System Company, U.S.A. By this program the data are converted such that a numerically controlled machine of the Fidia Company, Turin, is controlled. Eventually, the numerically controlled machine controls a milling machine of the Bohner and Koehle Company in Esslingen, Germany, for producing a reflector for a vehicular headlight according to the invention.

#### Claims

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1. A vehicular headlight capable of projecting on a flat target surface a predetermined illumination pattern, said headlight including a reflector having an optically effective surface, characterized by point asymmetry in substantially all planes cutting said optically effective surface.

- 2. A headlight capable of projecting on a flat target surface a predetermined illumination pattern, said headlight including a reflector having an optically effective surface, characterized by point asymmetry in substantially all planes cutting the said optically effective surface in optically perpendicular relation to the target surface.
- 3. A headlight capable of projecting on a flat target surface a predetermined illumination pattern, said headlight including a reflector having an optically effective surface characterized by axial asymmetry in all portions of the optically effective surface.
- 4. A headlight capable of projecting on a flat target surface a predetermined illumination pattern, said headlight including a reflector having an optically effective surface with an indefinite axial region generally located centrally of the optically effective surface and, all sectors of said optically effective surface located in opposed relation to the axial region being asymmetric.
- 5. A headlight capable of projecting on a flat target surface a predetermined illumination pattern, said headlight including an optically reflective surface with an indefinite axial region generally located centrally thereof and within the boundaries of a vertically centered horizontal band of approximately half the height of the optically effective surface, substantially all of such sectors being located in opposed relation to the axial region within said band being asymmetric.
- 6. A headlight capable of projecting onto a flat target surface a predetermined illumination pattern, said headlight including a reflector with a reflecting sector, characterized by asymmetry of sectors of said surface extending in opposed relation to each other from opposite sides of the reflecting surface adjacent a horizontal central plane cutting said surface.
- 7. A headlight according to claim 1, characterized in that the optically effective surface is reflective surface (1).
- 8. A headlight according to claim 1 or 7, characterized in that the optically effective surface is a surface of an optical element (2) arranged in the light beam reflected by the reflective surface.
- 9. A headlight according to any of claims 1 through 8, characterized in that the optically effective surface satisfies one single mathematical formula.
- 10. A headlight according to claim 9, characterized in that the optically effective surface is designed according to the following formula:

$$X = \frac{\frac{\text{rho}^2}{\text{R (phi)}}}{1 + \sqrt{1 - (K(\text{phi}) + 1) \cdot \frac{\text{rho}^2}{R(\text{phi})}}} + \frac{\text{n=ne}}{\text{n=0}} AK_n(\text{phi}) \cdot \text{rho}^n,$$

wherein

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$$R(phi) = \frac{m = me}{m = 0} [Rc_m \cdot cos(m \cdot phi) + Rs_m \cdot sin(m \cdot phi)],$$

$$K(phi) = \frac{i = ie}{\frac{1}{i}} [Kc_{i} \cdot cos(i \cdot phi) + Ks_{i} \cdot sin(i \cdot phi)],$$

$$AK_{n}(phi) = \frac{k = ke}{\sqrt{\frac{/}{k = 0}}} [AKc_{nk} \cdot cos(k \cdot phi) + AKs_{nk} \cdot sin(k \cdot phi)]$$

and wherein

X represents a linear cylindrical coordinate of the headlight axis which extends substantially in the direction of the light beam produced by the optically effective surface.

rho is the radius vector of said cylindrical coordinates,

phi represents the polar angles of said cylindrical coordinates of the loci,

n represents integers from 0 through 50, preferably through 10,

m, i and k represents integers from 0 through at least 3, preferably through 20,

R(phi) represents a coefficient which depends on phi and defines the limit value of the radii of curvature of the conic part of the surface at the apex with axial planes extending through the headlight axis when X = 0,

K(phi) represents a conic section coefficient as a function of phi,

 $AK_n(phi)$  represents one of ne + 1 different aspheric coefficients as functions of phi.

Rcm and Rsm each represent one of me + 1, and

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Kci and Ksi each represent one of ie + I different constant parameters,

 $AKc_{nk}$  and  $AKs_{nk}$  each represents one of (ne + 1) (ke + 1) different constant parameters.

- 11. A headlight according to claim 10, characterized by the values given in Table I for the parameters  $Rc_m$ ,  $Rs_m$ ,  $Kc_i$ ,  $Ks_i$ ,  $AKc_{nk}$  and  $AKs_{nk}$ .
- 12. A headlight according to one of claims 1 through 11, characterized in that the optical element (2) is arranged coaxially to the headlight axis (4).
- 13. A headlight according to one of claims 1 through 9, characterized in that the optical element (2) is eccentrically to the headlight axis (4).
- 14. A headlight according to one of claims 8 through 13, characterized in that between reflector (1) and optical element (2) a heat reflection filter and/or a cold mirror are/is arranged.
- 15. A headlight according to one of claims 1 through 14, characterized in that the reflector (1) is designed as a cold mirror.
- 16. A headlight according to one of claims 8 through 12, characterized in that the optical element (2) consists of plastic material.
  - 17. A headlight according to one of claims 8 through 16, characterized in that the optical element (2) consists of a colored material or is provided with a colored filter layer.
- 18. A headlight according to one of claims 8 through 17, characterized in that at least the surface of the optical element (2) having the largest distance from the opening of reflector (1) is scratch-resistant.
  - 19. The method for producing an optical surface comprising the steps of:

mathematically representing said surface by creating a spline from bivariate tensor product of polynomials; deriving mathematical data in computer input format from said mathematical representation; and inputting said data to a computer for controlling an apparatus by which the mathematical representation of said optical surface is reproduced in physical form.

20. The method for producing an optical surface comprising the steps of:

formulating a mathematical representation of an approximation of said optical surface, said representation having mathematical properties such that mathematical manipulation of local regions does not influence optical properties of other regions,

mathematically manipulating local regions of said representation until the resulting mathematical surface representation achieves the desired optical properties,

deriving from the resulting mathematical representation computer input data in computer input format, and

inputting said data to a computer for controlling an apparatus by which the mathematical representation of said optical surface is reproduced in physical form.

21. The method according to claim 20, in which the mathematical representation of an optical surface includes the steps of mathematically representing an approximation of said optical surface including an optical axis:

dividing said mathematical representation of said approximated surface into quadrangular initial surface segments by means of two families of planes which intersect said approximated surface representation, the planes of each of said families being parallel to each other and to said optical axis, and the planes of one of said families being normal to the planes of the other of said families;

determining the position of the corners of each of said initial surface segments;

determining the coefficients of initial bivariate polynomials from said corners, which coefficients define further surface segments approximated to said initial surface segments; and

varying the corners of said further surface segments step by step parallel to said axis for determining the coefficients of subsequent surface segments until the resulting mathematical representation achieves the desired optical properties.

- 22. The method according to claim 21, in which the step of determining the coefficients of initial bivariate polynomials from said corners is further characterized by using the Bezier method for calculating the coefficients ( $b_{co}$  through  $b_{33}$ ) of the initial and further polynomials from the corners ( $b_{co}$ ,  $b_{co}$ ,  $b_{30}$ ,  $b_{30}$ ) of said initial and further surface segments.
  - 23. The method according to claim 19, 21 or 22, further characterized by the step of: using cubic polynomials for adjacent further and subsequent surface segments having common sides; said surface segments being equal within their common sides through the second derivatives of their
  - 24. The method for producing an optical surface comprising the steps of:

determining bivariate polynomials describing initial surface segments having desired optical properties of a region of said optical surface;

determining further bivariate polynomials describing further initial surface segments located adjacent to said region;

determining additional bivariate polynomials which describe additional surface segments adjacent to already determined regions until an approximate surface to said optical surface is achieved;

changing locally said approximate surface by varying coefficients of said polynomials while retaining continuity through the second derivatives within the varied region without influencing optical properties of other regions of said approximate surface until the resulting representation of said optical surface achieves desired optical properties;

deriving from the resulting mathematical representation computer input data in computer input format; and

inputting said data to a computer for controlling an apparatus by which the mathematical representation of said optical surface is reproduced in physical form.

- 25. The method according to claim 24 wherein the steps of determining said further and said additional bivariate polynomials as well as varying said coefficients of said polynomials are achieved by the B-spline method.
  - 26. The method for producing an optical surface comprising the steps of: mathematically representing said surface by means of the the formula

$$X = \frac{\frac{\text{rho}^2}{\text{R (phi)}}}{1 + \sqrt{1 - (K(\text{phi}) + 1) \cdot \frac{\text{rho}^2}{R(\text{phi})}}} + \frac{\text{n=ne}}{\frac{\text{n=ne}}{R(\text{phi})}} AK_n(\text{phi}) \cdot \text{rho}^n,$$

wherein

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polynomials.

$$R(phi) = \frac{\frac{n = me}{\sqrt{\frac{m - me}{m}}} [Rc_m \cdot cos(m \cdot phi) + Rs_m \cdot sin(m \cdot phi)],$$

$$K(phi) = \frac{\underline{i} = \underline{ie}}{\sqrt{\frac{f_i \cdot \cos(i \cdot phi) + Ks_i \cdot \sin(i \cdot phi)}{f_i = 0}}} [Kc_i \cdot \cos(i \cdot phi) + Ks_i \cdot \sin(i \cdot phi)],$$

$$AK_{n}(phi) = \frac{k = ke}{\frac{k}{k} = 0} [AKc_{nk} \cdot cos(k \cdot phi) + AKs_{nk} \cdot sin(k \cdot phi)]$$

and wherein

X represents a linear cylindrical coordinate of the headlight axis which extends substantially in the

#### 0 282 100

direction of the light beam produced by the optically effective surface,

rho is the radius vector of said cylindrical coordinates,

phi represents the polar angle of said cylindrical coordinates of the loci,

n represents integers from 0 through 50, preferably through 10,

m, i and k represents integers from 0 through at least 3, preferably through 20.

R(phi) represents a coefficient which depends on phi and defines the limit value of the radii of curvature of the conic part of the surface at the apex with axial planes extending through the headlight axis when X = 0,

K(phi) represents a conic section coefficient as a function of phi,

AK<sub>n</sub>(phi) represents one of ne+1 different aspheric coefficients as functions of phi,

Rcm and Rsm each represent one of me + 1, and

Kc, and Ks, each represent one of ie + 1 different constant parameters.

AKc<sub>nk</sub> and AKs<sub>nk</sub> each represents one of (ne + 1) (ke + 1) different constant parameters.

deriving from the resulting mathematical representation computer input data in computer input format;

inputting said data to a computer for controlling an apparatus by which the mathematical representation of said optical surface is reproduced in physical form.

- 27. The method according to one of the claims 19 through 26, including the additional step of programming said computer to control said apparatus to physically reproduce said optical surface in the form of a mold by which a surface of a vehicular headlight can be replicated.
- 28. The method according to one of the claims 19 through 26, including the additional step of programming said computer to control said apparatus to physically reproduce said optical surface in the form in which said surface is required in said headlight.

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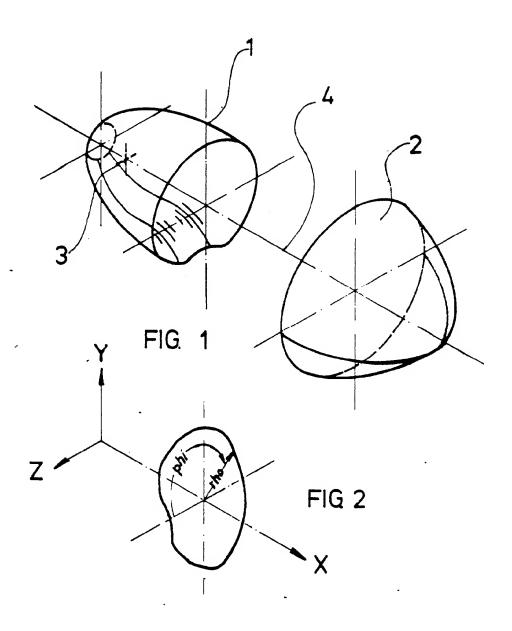
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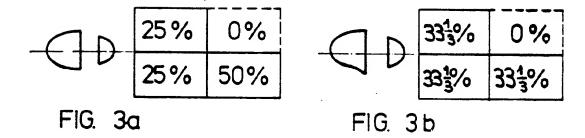
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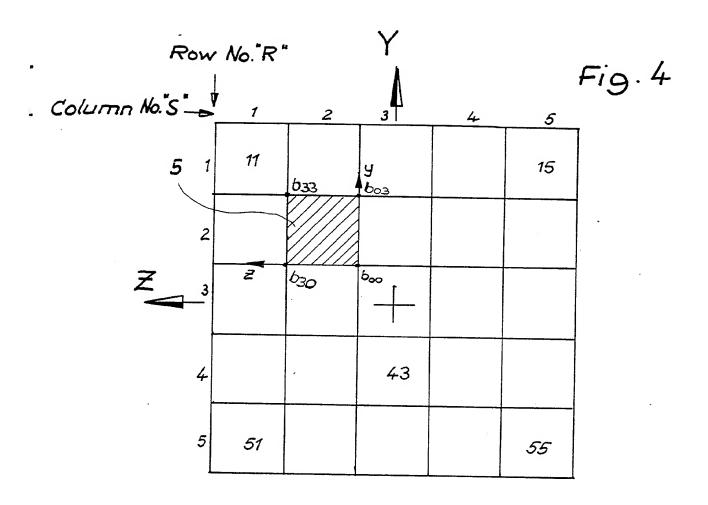
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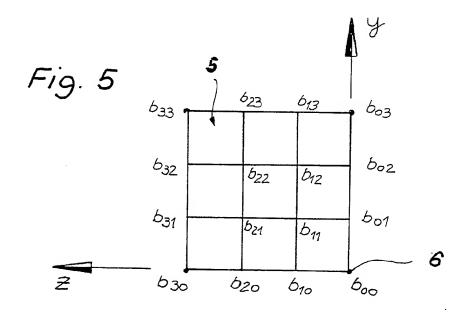
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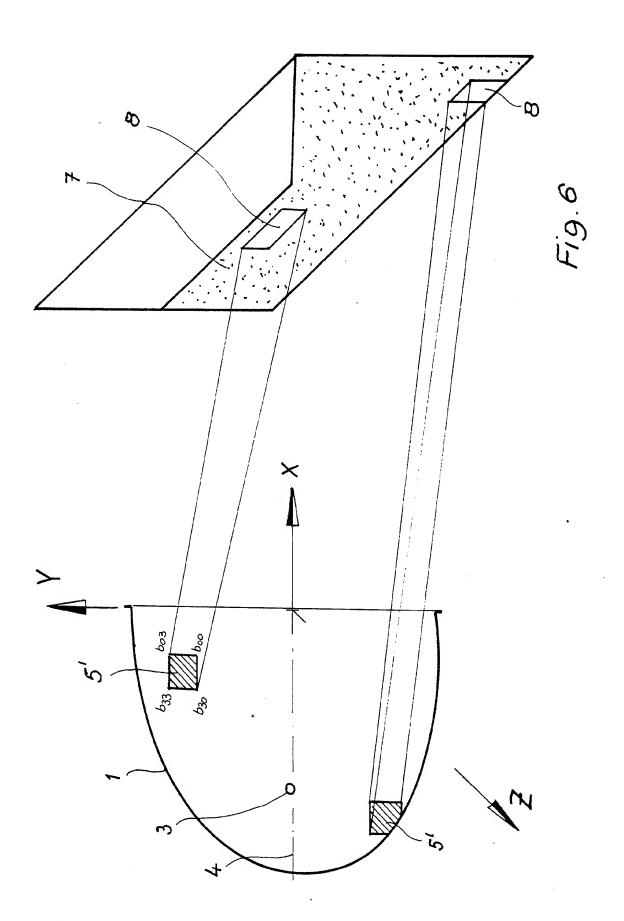


Table I, Page 1

# Reflector surface formula parameters for the first embodiment


## Reflector Surface

m	$Rc_m$	Rs <sub>m</sub>
0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20	0.301025616E+02 -0.776138504E+00 0.133370183E+01 0.215025141E+00 0.268470260E+00 0.184987154E+00 0.129671173E+00 0.637230940E-01 0.657042305E-01 0.423533490E-01 0.335088888E-01 0.137164324E-01 0.139906237E-01 0.732057473E-02 0.422798314E-02 -0.408471796E-05 -0.704443620E-04 -0.860155419E-04 -0.860155419E-04 -0.110987691E-02 -0.897140376E-03 -0.131258234E-02	0.000000000E+00 0.320000048E+01 0.130136414E+01 0.869100269E+00 0.200731876E+00 0.351886168E-01 -0.403600103E-01 0.320512819E-02 -0.106397102E-01 -0.160708906E-01 -0.192834327E-01 -0.874839426E-02 -0.376991649E-02 -0.376991649E-02 -0.420884650E-02 -0.420884650E-02 -0.212006914E-02 0.516378266E-03 -0.110971614E-02 -0.342223479E-03 0.107453809E-03 0.000000000E+00
i	Kc <sub>i</sub>	Ks <sub>i</sub>
0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20	-0.429484813E+00 -0.163727284E-01 -0.198936600E-01 -0.308477079E-01 -0.141336284E-01 -0.167193963E-01 -0.595014034E-02 -0.601753028E-02 -0.324424750E-02 -0.339949576E-02 -0.153724151E-02 -0.113067112E-02 -0.665049967E-03 -0.521768369E-03 -0.521768369E-03 -0.176222083E-03 -0.167376998E-04 0.666650797E-06 -0.647191699E-05 0.572639607E-04 0.325077313E-04 0.541442594E-04	0.00000000E+00 0.337263117E-01 -0.608890656E-02 0.338959596E-01 -0.271903061E-02 0.727648203E-03 -0.238452148E-03 0.677091093E-05 -0.259145831E-03 -0.629192629E-03 0.366436132E-04 -0.259073714E-03 -0.114321751E-04 -0.175471175E-03 0.411897732E-04 -0.221832787E-04 0.468744564E-05 -0.125775018E-04 0.108406081E-04 0.152450517E-04

Table I, Page 2

# Parameters $\mathtt{AKc_{n\;k}}$ and $\mathtt{AKs_{n\;k}}$

k	AKC <sub>4 k</sub>	AKs <sub>4 k</sub>
0	0.231351989E-06	0.00000000E+00
1	0.428899918E-06	-0.108098732E-06
2	-0.760933804E-06	-0.171556708E-06
3	-0.139034183E-06	-0.114824840E-06
4	-0.139181386E-06	-0.900163969E-08
5 6	-0.113484337E-06	-0.113165928E-07
6	-0.692201245E-07	0.958364387E-08
7	-0.388947559E-07	-0.430786403E-08
8	-0.350219486E-07	0.439361829E-08
9	-0.254912711E-07	0.126138438E-09
10 11	-0.181330145E-07 -0.818303372E-08	0.301827822E-08 0.367433193E-09
12	-0.818303372E-08 -0.757240546E-08	0.367433193E-09 0.721395733E-09
13	-0.434684382E-08	0.626818371E-09
14	-0.232837908E-08	0.302391591E-09
15	0.757435359E-11	0.282154895E-09
16	0.501081833E-10	-0.165543715E-09
17	0.278723188E-10	0.185979282E-09
18	0.615322577E-09	-0.568771854E-10
19	0.499060558E-09	0.672723983E-11
20 .	0.747285538E-09	0.00000000E+00
k	AKc <sub>6 k</sub>	AKs <sub>6 k</sub>
0	0.389873399E-09	0.00000000E+00
1	-0.517405133E-09	0.116609985E-09
2	-0.987346505E-10	-0.333227667E-09
3 4 5 6 7	0.961538761E-10	0.683053625E-10
4	0.199160759E-09	-0.683418244E-10
5	0.757325818E-10	0.331761612E-11
5	0.618804033E-10	0.635190239E-11
8	0.236550982E-10 0.311269008E-10	0.810501473E-12 -0.263245260E-12
9	0.153069516E-10	-0.263243260E-12 -0.918383261E-12
10	0.111863867E-10	0.436905887E-11
11	0.429446358E-11	-0.472278719E-12
12	0.451515603E-11	0.616508050E-12
13	0.244626543E-11	-0.394652800E-12
14	0.715797983E-12	0.123305623E-11
15	-0.109601896E-12	-0.108762629E-12
16	0.197247490E-12	-0.975652160E-13
17	0.946855192E-13	-0.643161886E-13
18	-0.479375138E-13	0.162114621E-12
19	-0.169187338E-12	0.154258155E-13
20	0.253073865E-12	0.00000000E+00

Table I, Page 3

# Parameters $AKc_{n k}$ and $AKs_{n k}$

k	AKC <sub>8 k</sub>	AKs <sub>8 k</sub>
0 1 2 3 4 5 6 7 8 9 0 1 1 1 2 1 3 1 1 1 1 1 1 1 1 1 1 1 1 1 1	-0.237072296E-12 -0.400715346E-12 0.279627689E-12 -0.163001548E-12 -0.160168487E-12 -0.796791834E-13 -0.462152595E-13 -0.309828591E-13 -0.241252882E-13 -0.168868959E-13 -0.168868959E-13 -0.616096672E-14 -0.332907991E-14 -0.332907991E-14 -0.385394236E-15 -0.193135632E-15 -0.193135632E-15 -0.171484070E-15 0.3882610016E-16 0.308505036E-16 0.208687007E-15 -0.266729468E-15	0.00000000E+00 0.822888353E-13 -0.184683304E-12 -0.161179791E-12 -0.438313897E-13 0.661726193E-14 0.208456218E-14 0.434925264E-14 -0.117592616E-14 0.492526452E-14 0.224656989E-14 0.152796660E-14 0.152796660E-14 0.249806639E-15 0.758992617E-15 -0.234130584E-15 -0.278481862E-16 -0.148401907E-15 0.121764340E-15 -0.154399611E-15 0.000000000E+00
k	AKC <sub>10k</sub>	AKs <sub>10k</sub>
0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20	0.713321483E-16 0.533706811E-15 0.164872968E-15 0.687919021E-16 -0.162835300E-17 0.246731742E-16 0.667927093E-17 0.126072927E-16 0.409966370E-17 0.626217680E-17 0.311769925E-17 0.297046067E-17 0.141248674E-17 0.103907576E-17 0.544805755E-18 0.206840560E-18 -0.632872999E-19 -0.108099972E-18 -0.214743921E-18 -0.149633902E-18 -0.305316901E-18	0.00000000E+00 -0.234348896E-15 -0.272667708E-16 -0.134748556E-15 -0.117704199E-17 -0.230461320E-17 0.158436254E-17 0.456377162E-18 0.742187412E-18 0.277419772E-17 0.487166504E-18 0.117760624E-17 0.118570563E-18 0.763942076E-18 0.763942076E-18 0.448408484E-19 0.115951610E-18 -0.274282156E-19 0.584383839E-19 -0.583100804E-19 0.0000000000E+00

Table II

	formula parameters for the fire	
 First lens surfa		
m	Rc <sub>m</sub>	Rs <sub>m</sub>
0	0.99999999E+35	0.00000000E+00
 Second lens sur		
m	Rc <sub>m</sub>	Rs <sub>m</sub>
0 -	-0.270000000E+02	0.000000000E+00
i	Kc <sub>i</sub>	Ks <sub>i</sub>
0 -	-0.16000000E+01	0.00000000E+00
k	AKc <sub>4 k</sub>	AKs <sub>4 k</sub>
0	0.16000000E-05	0.00000000E+00
k	AKc <sub>6 k</sub>	AKs <sub>6 k</sub>
0	-0.910000000E-08	0.00000000E+00
k	AKc <sub>8 k</sub>	AKs <sub>8 k</sub>
0	0.25000000E-11	0.00000000E+00

P Note:

Rotational symmetry is indicaced if only the value shown in the top row of a coefficient column (table 1) is other than zero, with values in all other rows being zero.

Table III, Page 1

Coefficients of the bivariate polynomials according to the Bezier method for the first embodiment

### REFLECTOR SURFACE

Segments(R,S) R 1 S 1 b(s,r), wherein (s,r) are the indices of "b" according to Fig.5

s 3	2	1	0
r 3 0.000 2 0.000 1 32.780 0 29.429	0.000 0.000 28.998 25.648	33.948 29.463 25.686 23.280	30.885 26.400 23.628 21.222
Segments(R,S) R 1 b(s,r) s 3	s 2 2	1	0
3 30.885 2 26.400 1 23.628 0 21.222	27.822 23.337 21.570 19.164	25.895 22.535 19.706 17.543	24.273 20.913 18:348 16.184
Segments(R,S) R 1 b(s,r) s 3	s 3	1	0
r 3 24.273 2 20.913 1 18.348 0 16.184	22.651 19.291 16.990 14.826	21.432 18.359 15.806 13.745	20.484 17.411 14.961 12.899
Segments(R,S) R 1 b(s,r) s 3	s 4 2	. 1	0
r 3 20.484 2 17.411 1 14.961 0 12.899	19.537 16.463 14.115 12.053	18.871 15.891 13.461 11.445	18.454 15.473 13.072 11.056
Segments(R,S) R 1 b(s,r)	s 5	1	-
s 3 r 3 18.454 2 15.473 1 13.072	2 18.037 15.056 12.683	1 17.869 14.885 12.513	0 17.939 14.954 12.548
0 11.056	10.667	10.498	10.533

Table III, Page 2

Segments b(s,r)	(R,S) R	1 s	6		
s	3		2	1	0
r 3 2 1 0	17.939 14.954 12.548 10.533		18.008 15.024 12.584 10.568	18.325 15.241 12.884 10.813	18.929 15.845 13.367 11.297
Segments b(s,r)	(R,S) R	1 s	7		
s	3		2	1	0
1 0	18.929 15.845 13.367 11.297		19.534 16.449 13.851 11.780	20.422 17.102 14.703 12.501	21.674 18.353 15.714 13.512
Segments b(s,r)	(R,S) R	1 s	8		
s	3		2	1	0
r 3 2 1 0	21.674 18.353 15.714 13.512		22.926 19.605 16.726 14.523	24.531 20.727 18.267 15.822	26.682 22.879 19.958 17.513
Segments	(R,S) R	1 s	9		•
b(s,r) s	3		2	1	0
3 2 1 0	26.682 22.879 19.958 17.513		28.834 25.031 21.648 19.203	31.382 26.047 24.163 21.274	35.462 30.127 26.856 23.967
Segments b(s,r)	(R,S) R	1 s1	10		·
s	3		2	1	0
3 2 1 0	35.462 30.127 26.856 23.967		39.543 34.208 29.549 26.660	0.000 0.000 33.989 29.743	0.000 0.000 39.038 34.793

Table III, Page 3

Segments b(s,r)	(R,S) R	2 s	1		
s	3		2	1	0
r 3 2 1 0	29.429 26.079 23.915 22.144		25.648 22.298 21.136 19.364	23.280 20.874 18.775 17.257	21.222 18.816 16.958 15.440
Segments b(s,r)	(R,S) R	2 S	2 .		
s	3		2	1	0
r 3 2 1 0	21.222 18.816 16.958 15.440		19.164 16.758 15.140 13.622	17.543 15.379 13.546 12.126	16.184 14.020 12.290 10.869
Segments b(s,r)	(R,S) R	2 s	3		
s	3		2	1	0
r 3 2 1 0	16.184 14.020 12.290 10.869		14.826 12.662 11.033 9.613	13.745 11.683 9.968 8.602	12.899 10.837 9.176 7.810
Segments b(s,r)	(R,S) R	2 s	4		
s	3		2	1	0
r 3 2 1 0	12.899 10.837 9.176 7.810		12.053 9.991 8.385 7.019	11.445 9.429 7.784 6.448	11.056 9.040 7.416 6.080
Segments b(s,r)		2 S			
s	3		2	1	0
r 3 2 1 0	11.056 9.040 7.416 6.080		10.667 8.651 7.047 5.711	10.498 8.482 6.878 5.546	10.533 8.517 6.897 5.564

Table III, Page 4

Segments b(s,r)	(R,S) R 2	S 6		
s	3	_ 2	1	0
r 3 2 1 0	10.533 8.517 6.897 5.564	10.568 8.552 6.915 5.583	10.813 8.742 7.150 5.789	11.297 9.226 7.567 6.205
Segments	(R,S) R 2	s 7		-
b(s,r) s	3	2	1	0
r 3 2 1	11.297 9.226 7.567 6.205	11.780 9.709 7.983 6.622	12.501 10.299 8.682 7.248	13.512 11.310 9.555 8.121
Segments b(s,r)	(R,S) R 2	s 8	•	
s	3	2	1	0
3 2 1 0	13.512 11.310 9.555 8.121	14.523 12.321 10.428 8.994	15.822 13.377 11.689 10.113	17.513 15.068 13.132 11.556
Segments	(R,S) R 2	s 9		
b(s,r)	3	2	1	0
7 3 2 1 0	17.513 15.068 13.132 11.556	19.203 16.758 14.575 12.999	21.274 18.386 16.590 14.763	23.967 21.079 18.836 17.008
Segments b(s,r)	(R,S) R 2	S10		
s	3	2	1	0 ·
3 2 1 0	23.967 21.079 18.836 17.008	26.660 23.772 21.082 19.254	29.743 25.498 24.247 21.952	34.793 30.547 27.825 25.529

Table III, Page 5

Segments b(s,r)	(R,S) R 3	s 1		
s	3	2	1	Ò
r 3 2 1 0	22.144 20.372 19.129 18.096	19.364 17.592 16.647 15.615	17.257 15.739 14.486 13.602	15.440 13.922 12.755 11.871
Segments b(s,r)	(R,S) R 3	S 2		
s r	3	2	1	0
3 2 1 0	15.440 13.922 12.755 11.871	13.622 12.104 11.025 10.140	12.126 10.705 9.550 8.700	10.869 9.449 8.342 7.491
Segments( b(s,r)		S 3		
r	3	2	1	0
3 2 1 0	10.869 9.449 8.342 7.491	9.613 8.192 7.133 6.283	8.602 7.236 6.138 5.310	7.810 6.445 5.376 4.548
Segments(	R,S) R 3	S 4		
b(s,r) s	3	2	1	0
3 2 1 0	7.810 6.445 5.376 4.548	7.019 5.653 4.614 3.786	6.448 5.112 4.053 3.236	6.080 4.743 3.696 2.880
Segments( b(s,r)	R,S) R 3	s 5		
r	3	2	1 .	0
3 2 1 0	6.080 4.743 3.696 2.880	5.711 4.375 3.340 2.523	5.546 4.213 3.178 2.362	5.564 4.232 3.188 2.372

Table III, Page 6

Segments( b(s,r)	(R,S) R	3 S	6		
s	3		2	1	0
r 3 2 1 0	5.564 4.232 3.188 2.372		5.583 4.250 3.198 2.382	5.789 4.427 3.399 2.569	6.205 4.844 3.781 2.951
Segments(b(s,r)		3 S	7		
s r	3		2	1	0
3 2 1 0	6.205 4.844 3.781 2.951		6.622 5.261 4.164 3.334	7.248 5.814 4.776 3.911	8.121 6.687 5.574 4.709
Segments	R,S) R	3 s	8		
b(s,r)	3		2	1	. 0
r 3 2 1 0	8.121 6.687 5.574 4.709		8.994 7.560 6.372 5.508	10.113 8.536 7.464 6.526	11.556 9.979 8.765 7.826
Segments	(R,S) R	3 S	9		
b(s,r)	3		2	1	0
r 3 2 1 0	11.556 9.979 8.765 7.826		12.999 11.422 10.065 9.127	14.763 12.935 11.786 10.707	17.008 15.181 13.781 12.702
Segments(b(s,r)	(R,S) R	3 S	10		
s	3		2	. 1	0
r 3 2 1 0	17.008 15.181 13.781 12.702		19.254 17.427 15.776 14.697	21.952 19.657 18.424 17.097	25.529 23.234 21.315 20.187

Table III, Page 7

Segments b(s,r)	(R,S) R 4	s 1		
s	3	2	. 1	0
r 3 2 1 0	18.096 17.064 16.246 15.779	15.615 14.583 13.917 13.450	13.602 12.718 11.986 11.553	11.871 10.987 10.333 9.900
Segments b(s,r)	(R,S) R 4	S 2		
s	3	. 2	1	0
r 3 2 1 0	11.871 10.987 10.333 9.900	10.140 9.256 8.680 8.247	8.700 7.850 7.247 6.852	7.491 6.641 6.067 5.672
Segments b(s,r)	(R,S) R 4	s 3		
s	3	2	1	0
r 3 2 1 0	7.491 6.641 6.067 5.672	6.283 5.433 4.887 4.491	5.310 4.481 3.891 3.524	4.548 3.720 3.131 2.764
Segments b(s,r)	(R,S) R 4	<b>S</b> 4		
s	3	2	1	0
3 2 1 0	4.548 3.720 3.131 2.764	3.786 2.958 2.371 2.004	3.236 2.419 1.835 1.453	2.880 2.063 1.477 1.095
Segments b(s,r)	(R,S) R 4	s 5		
S	3	2	1	0
3 · · · · · · · · · · · · · · · · · · ·	2.880 2.063 1.477 1.095	2.523 1.706 1.119 0.737	2.362 1.546 0.964 0.575	2.372 1.556 0.969 0.579

Table III, Page 8

Segments b(s,r)	(R,S) R 4	S 6		
, s	3	2	1	0
r 3 2 1 0	2.372 1.556 0.969 0.579	2.382 1.566 0.973 0.584	2.569 1.739 1.155 0.762	2.951 2.121 1.525 1.131
Segments b(s,r)	(R,S) R 4	s 7		
s	3	2	1	0
1 0	2.951 2.121 1.525 1.131	3.334 2.504 1.894 1.501	3.911 3.046 2.461 2.059	4.709 3.844 3.228 2.826
Segments b(s,r)		S 8		
s r	3	2	1	0
3 2 1	4.709 3.844 3.228 2.826	5.508 4.643 3.995 3.593	6.526 5.587 4.992 4.566	7.826 6.887 6.225 5.799
Segments	(R,S) R 4	<b>s</b> 9		
b(s,r) s	3	2	1	0
3 2 1 0	7.826 6.887 6.225 5.799	9.127 8.188 7.457 7.031	10.707 9.628 9.003 8.520	12.702 11.623 10.867 10.384
Segments b(s,r)		S10		
s r	3	2	1	0
3 2 1 0	12.702 11.623 10.867 10.384	14.697 13.618 12.732 12.249	17.097 15.769 15.078 14.483	20.187 18.860 17.933 17.338

Table III, Page 9

Segments b(s,r)	(R,S) R 5	s 1		
s	3	2	1	0
r 3 2 1 0	15.779 15.312 15.179 15.609	13.450 12.983 12.753 13.184	11.553 11.120 10.975 11.235	9.900 9.467 9.284 9.545
Segments b(s,r)	(R,S) R 5	S 2		
s	3	2	1	0
r 3 2 1 0	9.900 9.467 9.284 9.545	8.247 7.814 7.594 7.854	6.852 6.457 6.271 6.438	5.672 5.277 5.074 5.241
Segments b(s,r)	(R,S) R 5	S 3		
s	3	2	1	0
3 2 1 0	5.672 5.277 5.074 5.241	4.491 4.096 3.877 4.043	3.524 3.157 2.967 3.069	2.764 2.396 2.194 2.295
Segments b(s,r)	(R,S) R 5	S 4		
s	3	2	1	0
3 2 1 0	2.764 2.396 2.194 2.295	2.004 1.636 1.420 1.522	1.453 1.072 0.901 0.950	1.095 0.714 0.521 0.569
Segments b(s,r)	(R,S) R 5	<b>s</b> 5		
s	3	2	1	0
3 2 1	1.095 0.714 0.521 0.569	0.737 0.356 0.141 0.189	0.575 0.186 0.000 0.000	0.579 0.190 0.000 0.000

Table III, Page 10

Segments b(s,r)	(R,S) R 5	S 6		
s	3	. 2	1	0
r 3 2 1 0	0.579 0.190 0.000 0.000	0.584 0.195 0.000 0.000	0.762 0.368 0.169 0.186	1.131 0.738 0.544 0.561
Segments b(s,r)	(R,S) R 5	s 7		
s r	3	2	1	0
3 2 1 0	1.131 0.738 0.544 0.561	1.501 1.108 0.919 0.936	2.059 1.657 1.466 1.500	2.826 2.424 2.235 2.269
Segments b(s,r)	(R,S) R 5	S 8		
s r	3	2	1	0
3 2 1 0	2.826 2.424 2.235 2.269	3.593 3.191 3.004 3.038	4.566 4.140 3.960 4.010	5.799 5.372 5.182 5.232
Segments(	(R,S) R 5	s 9		
b(s,r) s	3	2	1	0
3 2 1 0	5.799 5.372 5.182 5.232	7.031 6.605 6.404 6.454	8.520 8.037 7.864 7.923	10.384 9.901 9.691 9.751
Segments(b(s,r)	R,S) R 5	S10		
r	3	. 2	1	0
3 2 1 0	10.384 9.901 9.691 9.751	12.249 11.766 11.519 11.578	14.483 13.888 13.702 13.758	17.338 16.743 16.479 16.536

Table III, Page 11

Segments(	(R,S) R	6 S	1		
b(s,r)	3	-	2	1	.0
r 3	15.609		13.184	11.235	9.545
2 1	16.039 17.160		13.614 14.241	11.495 12.556	9.805 10.614
0	19.011		16.092	13.832	11.890
Segments( b(s,r)	(R,S) R	6 S	2		
s	3		2	1	0
3 2	9.545 9.805		7.854 8.114	6.438 6.604	5.241 5.407
1	10.614		8.672	7.411	6.049
0	11.890		9.948	8.346	6.984
Segments( b(s,r)	(R,S) R	6 S	3		
s r	3		2	1	0
3 2	·5.241 5.407		4.043	3.069 3.170	2.295 2.396
1 0	6.049		4.686 5.621	3.835 4.496	2.919 3.580
		<i>e</i>		4.420	3.360
Segments ( b(s,r)	-	6 S	4		
r	3		2	1	0
3 2	2.295 2.396		1.522 1.623	0.950 0.998	0.569 0.617
1	2.919 3.580		2.003 2.664	1.453 1.964	0.962 1.473
Segments		6 S	•		
b(s,r)	3	•	2	1	0
r					
3 2	0.569 0.617		0.189	0.000	0.000
1 0	0.962 1.473		0.470 0.981	0.239 0.698	0.223 0.683

Table III, Page 12

Segments b(s,r)	(R,S) R 6	s 6			
s	3		2	1	0
r 3 2 1 0	0.000 0.000 0.223 0.683	0.0 0.0 0.2 0.6	0 0 0 8	0.186 0.203 0.407 0.859	0.561 0.578 0.796 1.248
Segments b(s,r)	(R,S) R 6	s 7			
s	3		2	. 1	0
7 3 2 1 0	0.561 0.578 0.796 1.248	0.9 0.9 1.1 1.6	53 86	1.500 1.534 1.757 2.223	2.269 2.303 2.552 3.019
Segments b(s,r)	(R,S) R 6	S 8			
s	. 3		2	1	0
r 3 2 1 0	2.269 2.303 2.552 3.019	3.0 3.0 3.3 3.8	72 48	4.010 4.060 4.310 4.818	5.232 5.282 5.563 6.071
Segments b(s,r)	(R,S) R 6	s 9			
s	3		2	1	0
r 3 2 1 0	5.232 5.282 5.563 6.071	6.4 6.5 6.8 7.3	04 15	7.923 7.982 8.258 8.824	9.751 9.810 10.119 10.684
Segments b(s,r)	(R,S) R 6	S10			
s	3		2	1	0
3 2 1 0	9.751 9.810 10.119 10.684	11.5 11.6 11.9 12.5	38 80	13.758 13.815 14.108 14.758	16.536 16.592 16.934 17.584

Table III, Page 13

<pre>Segments(R,S) R b(s,r)</pre>	7 s 1			
s 3	2	1	0	
19.011 2 20.862 1 23.449 0 27.095	16.092 17.942 19.053 22.699	13.832 15.107 17.471 19.555	11.890 13.165 14.851 16.935	
Segments(R,S) R b(s,r)	7 S 2			
s 3	2	1	0	
3 11.890 2 13.165 1 14.851 0 16.935	9.948 11.223 12.230 14.315	8.346 9.281 10.770 12.256	6.984 7.919 9.041 10.527	•
Segments(R,S) R b(s,r)	7 s 3			
s 3	2	1	0	
7 6.984 2 7.919 1 9.041 0 10.527	5.621 6.556 7.312 8.798	4.496 5.157 6.233 7.411	3.580 4.241 5.115 6.294	
Segments(R,S) R	7 s 4			
b(s,r) s 3	2	1	0	
3 3.580 2 4.241 1 5.115 0 6.294	2.664 3.325 3.998 5.176	1.964 2.475 3.303 4.331	1.473 1.983 2.720 3.748	
Segments(R,S) R b(s,r)	7 s 5			
s 3	2	1	0	
1.473 2 1.983 1 2.720 0 3.748	0.981 1.492 2.138 3.165	0.698 1.158 1.871 2.846	0.683 1.142 1.837 2.812	~

Table III, Page 14

Segmen b(s,r)	ts(R,S) R	7 S 6		
r	<b>s</b> 3	2	1	0
r 3 2 1 0	0.683 1.142 1.837 2.812	0.668 1.127 1.803 2.778	0.859 1.311 1.993 2.957	1.248 1.700 2.385 3.349
Segment b(s,r)	s(R,S) R 7	s 7		
r	s 3	2	1	0
3 2 1 0	1.248 1.700 2.385 3.349	1.638 2.089 2.777 3.741	2.223 2.690 3.361 4.345	3.019 3.486 4.186 5.170
Segment b(s,r)		S 8		
r	s 3	2	1	0
3 2 1 0	3.486 4.186 5.170	3.815 4.282 5.011 5.995	4.818 5.327 6.000 7.040	6.071 6.579 7.311 8.351
Segment: b(s,r)	s(R,S) R 7	<b>s</b> 9		
r	3	2	1	0
3 2 1 0	6.071 6.579 7.311 8.351	7.324 7.832 8.623 9.663	8.824 9.389 10.095 11.237	10.684 11.249 12.059 13.200
Segments b(s,r)	(R,S) R 7	S10		
s	3	2	1	0
3 2 1 0	10.684 11.249 12.059 13.200	12.545 13.110 14.022 15.164	14.758 15.407 16.158 17.506	17.584 18.234 19.187 20.536

Table III, Page 15

Segments b(s,r)	(R,S) R 8	s 1	·	
s	3	2	1	_ 0
r 3 2 1	27.095 30.741 24.902 46.937	22.699 26.345 3.951 25.982	19.555 21.639 25.550 29.364	16.935 19.019 21.545 25.359
Segments b(s,r)	(R,S) R 8	S 2		
s	3	2	• 1	0
r 3 2 1 0	16.935 19.019 21.545 25.359	14.315 16.399 17.541 21.354	12.256 13.742 16.126 18.583	10.527 12.013 13.840 16.297
Segments b(s,r)	(R,S) R 8	S 3		
s	3	2	1	0
7 3 2 1 0	10.527 12.013 13.840 16.297	8.798 10.284 11.554 14.012	7.411 8.590 10.332 12.271	6.294 7.472 8.951 10.889
Segments b(s,r)	(R,S) R 8	S 4		
s	3	2	1	0
r 3 2 1 0	6.294 7.472 8.951 10.889	5.176 6.355 7.569 9.508	4.331 5.358 6.785 8.496	3.748 4.776 6.089 7.800
Segments b(s,r)	(R,S) R 8	s 5	•	
s	3	2	1	0
3 2 1 0	3.748 4.776 6.089 7.800	3.165 4.193 5.393 7.104	2.846 3.820 5.099 6.725	2.812 3.786 5.038 6.664

Table III, Page 16

Segments b(s,r)	(R,S) R	8 S	6		
s	3		2	1	0
r 3 2 1	2.812 3.786 5.038 6.664		2.778 3.752 4.977 6.603	2.957 3.921 5.157 6.769	3.349 4.313 5.554 7.167
Segments b(s,r)	(R,S) R	8 s	7		
s	3		2	1	0
r 3 2 1 0	3.349 4.313 5.554 7.167		3.741 4.706 5.952 7.564	4.345 5.329 6.545 8.192	5.170 6.154 7.419 9.066
Segments b(s,r)	(R,S) R	8 S	8		
s	3		2	1	0
3 2 1 0	5.170 6.154 7.419 9.066		5.995 6.979 8.293 9.940	7.040 8.080 9.310 11.057	8.351 9.391 10.728 12.475
Segments	(R,S) R 8	8 s	9		
b(s,r) s	3		2	1	0
3 2 1 0	8.351 9.391 10.728 12.475		9.663 10.702 12.146 13.894	11.237 12.378 13.649 15.606	13.200 14.341 15.819 17.776
Segments b(s,r)	(R,S) R 8	3 S1	0		
r	3		2	1	0
3 2 1 0	13.200 14.341 15.819 17.776		15.164 16.305 17.988 19.946	17.506 18.855 20.120 22.547	20.536 21.885 23.628 26.054

Table III, Page 17

Segments b(s,r)		S 1		
s r	3 ·	2	1	0
3 2 1 0	46.937 68.976 0.000 0.000	25.982 48.017 0.000 0.000	29.364 33.177 0.000 0.000	25.359 29.173 0.000 0.000
Segments	(R,S) R 9	S 2		
b(s,r) s	3	2	1	0
3 2 1 0	25.359 29.173 0.000 0.000	21.354 25.168 0.000 0.000	18.583 21.041 25.410 30.180	16.297 18.755 21.686 26.456
Segments	(R,S) R 9	s 3		
b(s,r)	3	2	1	0
r 3 2 1	16.297 18.755 21.686 26.456	14.012 16.469 17.962 22.732	12.271 14.210 17.085 20.338	10.889 12.828 15.196 18.450
Segments	(R,S) R 9	S 4		
b(s,r) s	3	2	1	0
r 3 2 1	10.889 12.828 15.196 18.450	9.508 11.447 13.308 16.561	8.496 10.207 12.507 15.255	7.800 9.511 11.606 14.354
Segments b(s,r)	(R,S) R 9	s 5		
s	3	. 2	1	0
3 2 1 0	7.800 9.511 11.606 14.354	7.104 8.815 10.704 13.452	6.725 8.351 10.388 12.963	6.664 8.290 10.282 12.856

Table III, Page 18

(s,r)
9. 10. 12. 15.
3 066 713 731 346
\$ 8  2  9.940 11.587 13.693 16.307  \$ 9
1 11.057 12.804 14.738 17.555
12.475 14.223 16.366 19.183

Table III, Page 19

Segments(R, b(s,r)	S) R10	s 1		
S	3	2	1	0
2 0 1 0	.000 .000 .000	0.000 0.000 0.000	0.000 0.000 0.000 0.000	0.000 0.000 0.000 0.000
Segments(R,	S) R10	S 2		
b(s,r)	3	2	1	0
2 0 1 0	.000 .000 .000	0.000 0.000 0.000 0.000	30.180 34.950 0.000 0.000	26.456 31.226 0.000 0.000
Segments(R,	S) R10	s 3		
b(s,r) s	3	2	1	0
2 31 1 0	.456 .226 .000	22.732 27.502 0.000 0.000	20.338 23.592 29.076 37.409	18.450 21.703 24.823 33.155
Segments(R,	S) R10	S 4		
b(s,r) . s	3	. 2	1	0
2 21 1 24	.450 .703 .823	16.561 19.814 20.569 28.901	15.255 18.003 21.827 26.933	14.354 17.102 20.331 25.436
Segments(R,	S) R10	s 5		
b(s,r) s	3	2	1	0
2 17 1 20	.354 .102 .331 .436	13.452 16.200 18.834 23.939	12.963 15.537 18.714 23.173	12.856 15.431 18.493 22.952

Table III, Page 20

Segments b(s,r)	(R,S) R10	s 6		
s	3	2	1	0
r 3 2 1 0	12.856 15.431 18.493 22.952	12.750 15.324 18.272 22.731	12.895 15.445 18.453 22.828	13.304 15.854 18.888 23.262
Segments b(s,r)	(R,S) R10	s 7		
s	3	2	1	0
1 0	13.304 15.854 18.888 23.262	13.714 16.263 19.323 23.697	14.384 16.999 19.879 24.466	15.346 17.960 21.059 25.645
Segments	(R,S) R10	s 8		
b(s,r)	3	2	1	0
r 3 2 1 0	15.346 17.960 21.059 25.645	16.307 18.922 22.238 26.825	17.555 20.372 23.011 28.396	19.183 22.000 25.264 30.648
Segments	(R,S) R10	s 9		
b(s,r) s	3	2	1	0
r 3 2 1 0	19.183 22.000 25.264 30.648	20.810 23.627 27.516 32.901	22.801 26.108 26.529 35.531	25.445 28.751 31.654 40.656
Segments b(s,r)	(R,S) R10	S10		
S		2	1	0
r 3 2 1	25.445 28.751 31.654 40.656	28.088 31.394 36.778 45.781	31.242 36.089 0.000 0.000	36.249 41.096 0.000 0.000

Table IV, Page 1

Coefficients of the bivariate polynomials according to the Bezier method for the first embodiment

## FIRST LENS SURFACE

Segments(R,S) R 1 S 1 b(s,r), wherein (s,r) are the indices of "b" according to Fig. 5

	s	3	2	1	0
r					
3	0	.000	0.000	0.000	0.000
2	0	.000	0.000	0.000	0.000
1	0	.000	0.000	0.000	0.000
0	. 0	.000	0.000	0.000	0.000

Table IV, Page 2

Coefficients of the bivariate polynomials according to the Bezier method for the first embodiment

## SECOND LENS SURFACE

Segments(R,S) R 1 S 1 b(s,r), wherein (s,r) are the indices of "b" according to Fig. 5

D(S,r)	, wnere	ein (s,i	) ar	e the	indices	of	"b"	according	to	Fig.	5
<b></b>	s	3		:	2		:	L		0	
2 1 0	-56.2 -51.6 -47.1 -43.1	68 17	-	51-668 47.11! 42.16 38.20	5 7	-42 -37	.117 .167 .463	7 -: L -:	43.1 38.2 33.8	207 353	
Segmen b(s,r)	ts(R,S)	R 1	s 2	,	,		:			0	
r 3 2 1 0	-43.1 -38.2 -33.8 -30.2	.57 .07 .53	- -	39.19 <sup>2</sup> 34.24 <sup>2</sup> 30.24 <sup>3</sup> 26.63	7 7 5	-31 -26	.792 .133 .833	2 – 3 3 – 3	32.9 28.3 24.5 21.4	997 338 518	
Segmen b(s,r)	ts(R,S)	R 1	<b>s</b> 3	2	2		1	_		0	
r 3 2 1 0	-32.9 -28.3 -24.5 -21.4	38 18	-: -:	30.201 25.543 22.203 19.11	3 3	-23 -20	.000 .750 .046	) – 2 5 – 1	26.3 22.0 18.7	100 150 107	
Segmen b(s,r)	ts(R,S)	R 1	S 4						٠		
r 3 2 1 0	-26.3 -22.0 -18.7 -16.0	00 50 07	- : - :	24.600 20.350 17.368 14.691	) ) 3	-19 -16	.396 .437 .207	-2 -1 -1	22.6 .8.6 .5.5	46 96	
Segmen b(s,r)	ts(R,S)	R 1	s 5	2	3		1			0	
r 3 2 1	-22.6 -18.6 -15.5 -13.1	04 46 96	-: -:	21.813 17.854 14.984	<b>3</b>	-17 -14	.432 .574 .620	-2 -1 -1	1.4 7.5 4.6	32 74 20	

Table IV, Page 3

Segment b(s,r)	s(R,S)	R 1	s	6		
	s.	3		2	1	0
r 3 2 1 0	-21.43 -17.57 -14.62 -12.24			-21.432 -17.574 -14.620 -12.246	-21.813 -17.854 -14.984 -12.538	-22.604 -18.646 -15.596 -13.149
Segment b(s,r)	s(R,S)	R 1	s	7		
	s	3		2	1	0
r 3 2 1 0	-22.60 -18.64 -15.59 -13.14	6		-23.396 -19.437 -16.207 -13.761	-24.600 -20.350 -17.368 -14.691	-26.300 -22.050 -18.707 -16.030
Segment b(s,r)	s(R,S)	R 1	s	8		
	s	3		2	, 1	0
7 3 2 1 0	-26.30 -22.05 -18.70 -16.03	0 7		-28.000 -23.750 -20.046 -17.368	-30.201 -25.543 -22.203 -19.117	-32.997 -28.338 -24.518 -21.432
Segment	s(R,S)	R 1	S	9		
	s	3		2	1	0
r 3 2 1	-32.99 -28.33 -24.51 -21.43	.8 .8		-35.792 -31.133 -26.833 -23.746	-39.197 -34.247 -30.245 -26.637	-43.157 -38.207 -33.853 -30.245
Segment b(s,r)	s(R,S)	R 1	S	10		
	s	3		2	1	0
3 2 1 0	-43.15 -38.20 -33.85 -30.24	7 3		-47.117 -42.167 -37.461 -33.853	-51.668 -47.115 -42.167 -38.207	-56.222 -51.668 -47.117 -43.157

Table IV, Page 4

Segments(R,S) R 2 b(s,r)	s 1		-
s 3	2	1	0
3 -43.157 2 -39.197 1 -35.792 0 -32.997	-38.207 -34.247 -31.133 -28.338	-33.853 -30.245 -26.833 -24.518	-30.245 -26.637 -23.746 -21.432
Segments(R,S) R 2 b(s,r)	S 2		
s 3	2	1	0
3 -30.245 2 -26.637 1 -23.746 0 -21.432	-26.637 -23.029 -20.660 -18.346	-23.746 -20.660 -17.862 -15.972	-21.432 -18.346 -15.972 -14.081
Segments(R,S) R 2 b(s,r)	s 3		
s 3 r	2	1	0
3 -21.432 2 -18.346 1 -15.972 0 -14.081	-19.117 -16.031 -14.081 -12.190	-17.368 -14.691 -12.413 -10.777	-16.030 -13.352 -11.322 -9.687
Segments(R,S) R 2	S 4		-
b(s,r) s 3	2	1	0
3 -16.030 2 -13.352 1 -11.322 0 -9.687	-14.691 -12.013 -10.232 -8.596	-13.761 -11.315 -9.353 -7.830	-13.149 -10.703 -8.845 -7.322
Segments(R,S) R 2 b(s,r)	s 5		
s 3	2	1	0
3 -13.149 2 -10.703 1 -8.845 0 -7.322	-12.538 -10.091 -8.337 -6.814	-12.246 -9.871 -8.062 -6.567	-12.246 -9.871 -8.062 -6.567

Table IV, Page 5

Segments(R,S) R 2 b(s,r)	S 6		
s 3	2	1	0
-12.246 2 -9.871 1 -8.062 0 -6.567	-12.246 -9.871 -8.062 -6.567	-12.538 -10.091 -8.337 -6.814	-13.149 -10.703 -8.845 -7.322
Segments(R,S) R 2	s 7		
b(s,r) s 3	2	1	0
-13.149 2 -10.703 1 -8.845 0 -7.322	-13.761 -11.315 -9.353 -7.830	-14.691 -12.013 -10.232 -8.596	-16.030 -13.352 -11.322 -9.687
Segments(R,S) R 2 b(s,r)	S 8		
s 3	2	1	0
-16.030 2 -13.352 1 -11.322 0 -9.687	-17.368 -14.691 -12.413 -10.777	-19.117 -16.031 -14.081 -12.190	-21.432 -18.346 -15.972 -14.081
Segments(R,S) R 2	<b>s</b> 9		
b(s,r) s 3	2	1	0
-21.432 2 -18.346 1 -15.972 0 -14.081	-23.746 -20.660 -17.862 -15.972	-26.637 -23.029 -20.660 -18.346	-30.245 -26.637 -23.746 -21.432
Segments(R,S) R 2 b(s,r)	S10		
s 3	2	1	. 0
3 -30.245 2 -26.637 1 -23.746 0 -21.432	-33.853 -30.245 -26.833 -24.518	-38.207 -34.247 -31.133 -28.338	-43.157 -39.197 -35.792 -32.997

Table IV, Page 6

<pre>Segments(R,S) b(s,r)</pre>	R 3	s	1		
S	3		2	1	0
7 -32.99 2 -30.20 1 -28.00 0 -26.30	)1 )0		-28.338 -25.543 -23.750 -22.050	-24.518 -22.203 -20.046 -18.707	-21.432 -19.117 -17.368 -16.030
<pre>Segments(R,S) b(s,r)</pre>	R 3	s	2		
s	3		2	1	0
7 -21.43 2 -19.13 1 -17.36 0 -16.03	L7 58		-18.346 -16.031 -14.691 -13.352	-15.972 -14.081 -12.413 -11.322	-14.081 -12.190 -10.777 -9.687
Segments(R,S) b(s,r)	R 3	s	3		
s r	3		2	1	0
3 -14.08 2 -12.19 1 -10.77 0 -9.68	90 77		-12.190 -10.299 -9.141 -8.051	-10.777 -9.141 -7.788 -6.807	-9.687 -8.051 -6.807 -5.826
Segments(R,S)	R 3	s	4		
b(s,r) s r	3		2	1	0
3 -9.68 2 -8.05 1 -6.80 0 -5.82	51 17		-8.596 -6.960 -5.826 -4.845	-7.830 -6.306 -5.088 -4.130	-7.322 -5.798 -4.609 -3.652
Segments(R,S) b(s,r)	R 3	s			
r .	3		2	1	0
3 -7.32 2 -5.79 1 -4.60 0 -3.65	) 8 ) 9		-6.814 -5.291 -4.130 -3.173	-6.567 -5.072 -3.892 -2.933	-6.567 -5.072 -3.892 -2.933

Table IV, Page 7

Segments(R,S) R 3 b(s,r)	s 6		
s 3	2	1	0
7 3 -6.567 2 -5.072 1 -3.892 0 -2.933	-6.567 -5.072 -3.892 -2.933	-6.814 -5.291 -4.130 -3.173	-7.322 -5.798 -4.609 -3.652
Segments(R,S) R 3 b(s,r)	s 7		
s 3	2	1	0
7.322 2 -5.798 1 -4.609 0 -3.652	-7.830 -6.306 -5.088 -4.130	-8.596 -6.960 -5.826 -4.845	-9.687 -8.051 -6.807 -5.826
Segments(R,S) R 3	S 8		
b(s,r) s 3	2	1	0
r 3 -9.687 2 -8.051 1 -6.807 0 -5.826	-10.777 -9.141 -7.788 -6.807	-12.190 -10.299 -9.141 -8.051	-14.081 -12.190 -10.777 -9.687
Segments(R,S) R 3	s 9		
b(s,r) s 3	2	1	0
r 3 -14.081 2 -12.190 1 -10.777 0 -9.687	-15.972 -14.081 -12.413 -11.322	-18.346 -16.031 -14.691 -13.352	-21.432 -19.117 -17.368 -16.030
Segments(R,S) R 3 b(s,r)	S10		
s 3	2	1	0
r 3 -21.432 2 -19.117 1 -17.368 0 -16.030	-24.518 -22.203 -20.046 -18.707	-28.338 -25.543 -23.750 -22.050	-32.997 -30.201 -28.000 -26.300

Table IV, Page 8

Segments( b(s,r)	R,S) R	4 S	1		
s	3		2	1	. 0
2 -	26.300 24.600 23.396 22.604		-22.050 -20.350 -19.437 -18.646	-18.707 -17.368 -16.207 -15.596	-16.030 -14.691 -13.761 -13.149
Segments( b(s,r)	R,S) R	4 S	2 .		
s	3		. 2	, 1	0.
2 -	16.030 14.691 13.761 13.149		-13.352 -12.013 -11.315 -10.703	-11.322 -10.232 -9.353 -8.845	-9.687 -8.596 -7.830 -7.322
Segments(	R,S) R	4 S	3		
b(s,r) s	3		2	1	0
r 3 2 1 0	-9.687 -8.596 -7.830 -7.322		-8.051 -6.960 -6.306 -5.798	-6.807 -5.826 -5.088 -4.609	-5.826 -4.845 -4.130 -3.652
Segments(	R,S) R	. 4 5	3 4		
b(s,r)	3		2	1	0
r 3 2 1 0	-5.826 -4.845 -4.130 -3.652		-4.845 -3.864 -3.173 -2.694	-4.130 -3.173 -2.461 -1.974	-3.652 -2.694 -1.974 -1.486
Segments(	R,S) R	4 5	5 5		
b(s,r)	3		2	1	0
r 3 2 1 0	-3.652 -2.694 -1.974 -1.486		-3.173 -2.215 -1.486 -0.999	-2.933 -1.975 -1.245 -0.750	-2.933 -1.975 -1.245 -0.750

Table IV, Page 9

Segments(R,S) R 4 b(s,r)	s 6		
s 3	2	1	0
-2.933 2 -1.975 1 -1.245 0 -0.750	-2.933 -1.975 -1.245 -0.750	-3.173 -2.215 -1.486 -0.999	-3.652 -2.694 -1.974 -1.486
Segments(R,S) R 4 b(s,r)	s 7		
s 3	2	1	0
3 -3.652 2 -2.694 1 -1.974 0 -1.486	-4.130 -3.173 -2.461 -1.974	-4.845 -3.864 -3.173 -2.694	-5.826 -4.845 -4.130 -3.652
Segments(R,S) R 4	s 8		
b(s,r) s 3	2	1	0
r 3 -5.826 2 -4.845 1 -4.130 0 -3.652	-6.807 -5.826 -5.088 -4.609	-8.051 -6.960 -6.306 -5.798	-9.687 -8.596 -7.830 -7.322
Segments(R,S) R 4	<b>s</b> 9		
b(s,r) s 3	2	1	0
-9.687 2 -8.596 1 -7.830 0 -7.322	-11.322 -10.232 -9.353 -8.845	-13.352 -12.013 -11.315 -10.703	-16.030 -14.691 -13.761 -13.149
Segments(R,S) R 4	<b>S10</b>		
b(s,r) s 3	2	1	0
-16.030 2 -14.691 1 -13.761 0 -13.149	-18.707 -17.368 -16.207 -15.596	-22.050 -20.350 -19.437 -18.646	-26.300 -24.600 -23.396 -22.604

Table IV, Page 10

Segments(R,S) R-5	s 1		
b(s,r) s 3	2	1	0
r 3	-18.646 -17.854 -17.574 -17.574	-15.596 -14.984 -14.620 -14.620	-13.149 -12.538 -12.246 -12.246
Segments(R,S) R 5 b(s,r)	s 2		_
s 3	2	1	0
3 -13.149 2 -12.538 1 -12.246 0 -12.246	-10.703 -10.091 -9.871 -9.871	-8.845 -8.337 -8.062 -8.062	-7.322 -6.814 -6.567 -6.567
Segments(R,S) R 5	s 3		
b(s,r) s 3	2	1	0
r 3	-5.798 -5.291 -5.072 -5.072	-4.609 -4.130 -3.892 -3.892	-3.652 -3.173 -2.933 -2.933
Segments(R,S) R 5	S 4		
b(s,r) s 3	2	1	0
r 3 -3.652 2 -3.173 1 -2.933 0 -2.933	-2.694 -2.215 -1.975 -1.975	-1.974 -1.486 -1.245 -1.245	-1.486 -0.999 -0.750 -0.750
Segments(R,S) R 5	s 5		
b(s,r) s 3	2	ı	0
r 3 -1.486 2 -0.999 1 -0.750 0 -0.750	-0.999 -0.512 -0.255 -0.255	-0.750 -0.255 0.000 0.000	-0.750 -0.255 0.000 0.000

Table IV, Page 11

Segments(R,S) R 5	<b>.</b> s 6		
b(s,r) s 3	2	1	0
7	-0.750 -0.255 0.000 0.000	-0.999 -0.512 -0.255 -0.255	-1.486 -0.999 -0.750 -0.750
Segments(R,S) R 5	s 7		
b(s,r) s 3	2	1	0
1 -1.486 2 -0.999 1 -0.750 0 -0.750	-1.974 -1.486 -1.245 -1.245	-2.694 -2.215 -1.975 -1.975	-3.652 -3.173 -2.933 -2.933
Segments(R,S) R 5	s 8		
b(s,r) s 3	2	1 .	0
r 3 -3.652 2 -3.173 1 -2.933 0 -2.933	-4.609 -4.130 -3.892 -3.892	-5.798 -5.291 -5.072 -5.072	-7.322 -6.814 -6.567 -6.567
Segments(R,S) R 5	s 9		
b(s,r) s 3	2	1	. 0
7.322 2 -6.814 1 -6.567 0 -6.567	-8.845 -8.337 -8.062 -8.062	-10.703 -10.091 -9.871 -9.871	-13.149 -12.538 -12.246 -12.246
Segments(R,S) R 5	<b>S10</b>		
b(s,r)	2	1	0
r 3 -13.149 2 -12.538 1 -12.246 0 -12.246	-15.596 -14.984 -14.620 -14.620	-18.646 -17.854 -17.574 -17.574	-22.604 -21.813 -21.432 -21.432

Table IV, Page 12

Segments b(s,r)	(R,S)	R 6	5 S	1		
s	:	3		2	. 1	0
2	-21.432 -21.432 -21.813 -22.604	2 3		-17.574 -17.574 -17.854 -18.646	-14.620 -14.620 -14.984 -15.596	-12.246 -12.246 -12.538 -13.149
Segments b(s,r)	(R,S)	R 6	s s	2		
s	3	3		2	1	2,2
2 1	-12.246 -12.246 -12.538 -13.149	5 }		-9.871 -9.871 -10.091 -10.703	-8.062 -8.062 -8.337 -8.845	-6.567 -6.567 -6.814 -7.322
Segments b(s,r)	(R,S)	R 6	s s	3		
r	3	3		2	1	0
3 2 1 0	-6.567 -6.567 -6.814 -7.322	? !		-5.072 -5.072 -5.291 -5.798	-3.892 -3.892 -4.130 -4.609	-2.933 -2.933 -3.173 -3.652
Segments b(s,r)	(R,S)	R 6	s s	4		
s	3	3		2	1	0
7 3 2 1 0	-2.933 -2.933 -3.173 -3.652	} }		-1.975 -1.975 -2.215 -2.694	-1.245 -1.245 -1.486 -1.974	-0.750 -0.750 -0.999 -1.486
Segments b(s,r)		R 6	s			
s r	3	}		2	1	0
3 2 1 0	-0.750 -0.750 -0.999 -1.486	) , .		-0.255 -0.255 -0.512 -0.999	0.000 0.000 -0.255 -0.750	0.000 0.000 -0.255 -0.750

Table IV, Page 13

Segments b(s,r)	(R,S)	R	6	s	6							
s		3				2			1			0
r 3 2 1 0	0.00 0.00 -0.25 -0.75	5			0. -0.	000 000 255 750	-0 -0	.25 .25 .51	5 2		-0. -0.	750 750 999 486
Segments	(R,S)	R	6	s	7							
b(s,r)		3				2		:	1			0
r 3 2 1 0	-0.75 -0.75 -0.99 -1.48	9			-1. -1.	245 245 486 974	-1 -2	.97 .97 .21	5 5		-2. -3.	933 933 173 652
Segments b(s,r)	(R,S)	R	6	s	8							
s		3				2			1			0
r 3 2 1 0	-2.93 -2.93 -3.17 -3.65	3			-3. -4.	892 892 130 609	-5 -5	.07; .07; .29;	2 1		-6. -6.	567 567 814 322
Segments	(R,S)	R	6	s	9							
b(s,r)		3				2		:	1			0
r 3 2 1 0	-6.56 -6.56 -6.81 -7.32	7			-8. -8.	062 062 337 845			l L		-12. -12. -12. -13.	246 538
Segments b(s,r)	(R,S)	R	6	s1	0							
s		3				2		:	L .			0
3 2 1	-12.24 -12.24 -12.53 -13.14	б 8			-14. -14. -14. -15.	620 984	-17 -17 -17 -18	.574 .854	4 4	,	-21. -21. -21.	432 813

Table IV, Page 14

Segments	(R,S)	R 7	s 1				
b(s,r)	3			2		1	0
2 -	-22.604 -23.396 -24.600 -26.300		-19 -20	.646 .437 .350	-15. -16. -17. -18.	207 368	-13.149 -13.761 -14.691 -16.030
Segments b(s,r)	(R,S)	R 7	s 2				
s	3			2		1	0
2 -	-13.149 -13.761 -14.691 -16.030		-11 -12	.703 .315 .013 .352			-7.322 -7.830 -8.596 -9.687
Segments b(s,r)	(R,S)	R 7	s 3				
5	3			2		1	0
r 3 2 1 0	-7.322 -7.830 -8.596 -9.687		-6 -6	.798 .306 .960	-5. -5.	609 088 826 807	-3.652 -4.130 -4.845 -5.826
Segments	(R,S)	R 7	s 4				
b(s,r)	3			2		1	0
r 3 2 1 0	-3.652 -4.130 -4.845 -5.826		-3 -3	.694 .173 .864 .845	-2. -3.	974 461 173 130	-1.486 -1.974 -2.694 -3.652
Segments b(s,r)	(R,S)	R 7	<b>s</b> 5				
s	. 3			2		1	0
r 3 2 1	-1.486 -1.974 -2.694 -3.652		-1 -2	.999 .486 .215 .173	-1. -1.	750 245 975 933	-0.750 -1.245 -1.975 -2.933

Table IV, Page 15

Segments(R,S) R 7	s 6		
b(s,r) s 3	2	1	0
7 3 -0.750 2 -1.245 1 -1.975 0 -2.933	-0.750 -1.245 -1.975 -2.933	-0.999 -1.486 -2.215 -3.173	-1.486 -1.974 -2.694 -3.652
Segments(R,S) R 7	s 7		
b(s,r) s 3	2	1	0
1 -1.486 2 -1.974 1 -2.694 0 -3.652	-1.974 -2.461 -3.173 -4.130	-2.694 -3.173 -3.864 -4.845	-3.652 -4.130 -4.845 -5.826
Segments(R,S) R 7	S 8		
b(s,r) s 3	2	1	0
r 3 -3.652 2 -4.130 1 -4.845 0 -5.826	-4.609 -5.088 -5.826 -6.807	-5.798 -6.306 -6.960 -8.051	-7.322 -7.830 -8.596 -9.687
Segments(R,S) R 7	s <sup>9</sup>		
b(s,r) s 3	2	1	0
r 3	-8.845 -9.353 -10.232 -11.322	-10.703 -11.315 -12.013 -13.352	-13.149 -13.761 -14.691 -16.030
Segments(R,S) R 7	<b>s</b> 10		
b(s,r) s 3	2	1	0
r 3 -13.149 2 -13.761 114.691 0 -16.030	-15.596 -16.207 -17.368 -18.707	-18.646 -19.437 -20.350 -22.050	-22.604 -23.396 -24.600 -26.300

Table IV, Page 16

Segments(R,S	S) R 8	s 1			
s	3		2	1	0
2 -28 1 -30	.300 .000 .201 .997	-2 -2	2.050 3.750 5.543 8.338	-18.707 -20.046 -22.203 -24.518	-16.030 -17.368 -19.117 -21.432
Segments(R,	5) R 8	s 2		-	
b(s,r) s	3		2	1	0
2 -17 1 -19	.030 .368 .117 .432	-1 -1	3.352 4.691 6.031 8.346	-11.322 -12.413 -14.081 -15.972	-9.687 -10.777 -12.190 -14.081
Segments(R,	S) R 8	s 3			
b(s,r) s	3		2	1	0
2 -10 1 -12	.687 .777 .190	-1	8.051 9.141 0.299 2.190	-6.807 -7.788 -9.141 -10.777	-5.826 -6.807 -8.051 -9.687
Segments(R,	s) R 8	s 4			
b(s,r) s	3		2	1	0
2 -6 1 -8	.826 .807 .051 .687	_	4.845 5.826 6.960 8.596	-4.130 -5.088 -6.306 -7.830	-3.652 -4.609 -5.798 -7.322
Segments(R,	s) R8	s 5			
b(s,r) s	3		2	1	0
2 -4 1 -5	.652 .609 .798 .322	 -	3.173 4.130 5.291 6.814	-2.933 -3.892 -5.072 -6.567	-2.933 -3.892 -5.072 -6.567

Table IV, Page 17

Segments b(s,r)	(R,S)	R	8	S	6						
s		3				2				1	0
r 3 2 1 0	-2.93 -3.89 -5.07 -6.56	) 2 ! 2			-3 -5	.933 .892 .072	•	-4 -5	.17 .13 .29	0 1	-3.652 -4.609 -5.798 -7.322
Segments	(R,S)	R	8	S	7						
b(s,r) s		3				2				1	o .
r 3 2 1 0	-3.65 -4.60 -5.79 -7.32	) 9 9 8			-5 -6	.130 .088 .306		-5 -6	.84 .82 .96	6 0	-5.826 -6.807 -8.051 -9.687
Segments	(R,S)	R	8	S	8						
b(s,r) s		3				2				1	0
r 3 2 1 0	-5.83 -6.80 -8.05 -9.68	)7 51			-7 -9	.807 .788 .141				1 9	-9.687 -10.777 -12.190 -14.081
Segments	(R,S)	R	8	s	9						
b(s,r) s		3				2				1	0
r 3 2 1 0	-9.68 -10.7 -12.19 -14.08	77 90			-12 -14	.322 .413 .081		-13 -14 -16 -18	.69 .03	1 1	-16.030 -17.368 -19.117 -21.432
Segments	(R,S)	R	8	S1	L 0						
b(s,r) s	i,	3				2				1	0
r 3 2 1	-16.03 -17.36 -19.13 -21.43	68 17			-20 -22	.707 .046 .203		-22 -23 -25 -28	.75 .54	0 3	-26.300 -28.000 -30.201 -32.997

Table IV, Page 18

Segments b(s,r)	s(R,S)	R	9	s	1						
:	5	3				2			1		0
r 3 2 1 0	-32.99 -35.79 -39.19 -43.15	) 2 ) 7			-28.33 -31.13 -34.24 -38.20	3 7			3 5	-23 -26	.432 .746 .637 .245
Segment: b(s,r)	s(R,S)	R	9	s	2						
	S	3 ,				2			1		0.
r 3 2 1 0	-21.43 -23.74 -26.63 -30.24	46 37			-18.34 -20.66 -23.02 -26.63	0 9	-17 -20	3.97 3.86 3.74	0	-15 -18	.081 .972 .346 .432
Segment	s(R,S)	R	9	s	3						
b(s,r)	s	3				2			1		0
r 3 2 1 0	-14.03 -15.9 -18.3 -21.4	72 46		٠	-12.19 -14.08 -16.03 -19.11	1 1	-12 -14	0.77 2.41 4.69 7.36	.3 91	-11 -13	.687 .322 .352 .030
Segment	s(R,S)	R	9	s	4						
b(s,r)	s	3				2			1		0
r 3 2 1 0	-9.6 -11.3 -13.3 -16.0	22 52			-8.59 -10.23 -12.01 -14.69	. 3	-9 -13	7.83 9.39 1.33	53 15	-8 -10	7.322 3.845 0.703 3.149
Segment	s(R,S)	R	9	s	5						
b(s,r)	s	3				2			1		0
r 3 2 1	-7.3 -8.8 -10.7 -13.1	45 03			-6.81 -8.33 -10.09 -12.53	37 91	_	6.5 8.0 9.8 2.2	62 71	-8 -9	5.567 3.062 9.871 2.246

Table IV, Page 19

Segments(R,S) R b(s,r)	9 S 6		
s 3	2	1	0
-6.567 2 -8.062 1 -9.871 0 -12.246	-6.567 -8.062 -9.871 -12.246	-6.814 -8.337 -10.091 -12.538	-7.322 -8.845 -10.703 -13.149
Segments(R,S) R	9 s 7		
b(s,r) s 3	2	1	0
r 3	-7.830 -9.353 -11.315 -13.761	-8.596 -10.232 -12.013 -14.691	-9.687 -11.322 -13.352 -16.030
Segments(R,S) R	9 S 8		
b(s,r) s 3	2	1	0
-9.687 2 -11.322 1 -13.352 0 -16.030	-10.777 -12.413 -14.691 -17.368	-12.190 -14.081 -16.031 -19.117	-14.081 -15.972 -18.346 -21.432
	9 S 9		·
b(s,r) s 3	2	1	0
r 3 -14.081 2 -15.972 1 -18.346 0 -21.432	-15.972 -17.862 -20.660 -23.746	-18.346 -20.660 -23.029 -26.637	-21.432 -23.746 -26.637 -30.245
	9 S10		
b(s,r) s 3	2	1	0
r 3 -21.432 2 -23.746 1 -26.637 0 -30.245	-24.518 -26.833 -30.245 -33.853	-28.338 -31.133 -34.247 -38.207	-32.997 -35.792 -39.197 -43.157

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Table IV, Page 20

Segments (b(s,r)	(R,S)	R10 S	s :	1									
s .	3				;	2				1			0
2 -	-43.157 -47.117 -51.668 -56.222			-38. -42. -47. -51.	16	7 5	-3 -4	33. 37. 12.	46 16	5 <b>1</b> 57		-30. -33. -38. -43.	853 207
Segments	(R,S)	R10	S	2									
b(s,r) s	3				•	2				1			0
2	-30.245 -33.853 -38.207 -43.157	•		-26. -30. -34.	24	5 7	-3 -3	23. 26. 31.	83	33 33		-21. -24. -28. -32.	518 338
Segments	(R,S)	R10	S	3									
b(s,r) s	3	3				2				1			0
2	-21.432 -24.518 -28.338 -32.99	3		-19 -22 -25 -30	.20 .54	3 3	- : - :	17 20 23 28	. 0 4 . 7 9	46 50		-16. -18. -22. -26.	.707 .050
Segments	(R,S)	R10	s	4									
b(s,r) s	;	3				2				1	3	_	0
	-16.030 -18.70 -22.050 -26.300	7 0		-14 -17 -20 -24	.36 .35	8	-	13 16 19 23	. 2	07 37		-15 -18	.149 .596 .646 .604
Segments	(R,S)	R10	s	5									
b(s,r)	3	3				2				1			0
r 3 2 1 0	-13.14 -15.59 -18.64 -22.60	6 6		-12 -14 -17 -21	.98	3 <b>4</b> 5 <b>4</b>	- -	12 14 17 21	.6 .5	20 74		-14 -17	.246 .620 .574 .432

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Table IV, Page 21

Segment	s(R,S) R10	s 6		
b(s,r)	s 3	2	1	0
r 3 2 1 0	-12.246 -14.620 -17.574 -21.432	-12.246 -14.620 -17.574 -21.432	-12.538 -14.984 -17.854 -21.813	-13.149 -15.596 -18.646 -22.604
Segment b(s,r)	s 3	s 7	1	
r 3 2 1	-13.149 -15.596 -18.646 -22.604	-13.761 -16.207 -19.437 -23.396	-14.691 -17.368 -20.350 -24.600	-16.030 -18.707 -22.050 -26.300
Segmen b(s,r)	ts(R,S) R10 s 3	s 8 2	. 1	0
r 3 2 1 0	-16.030 -18.707 -22.050 -26.300	-17.368 -20.046 -23.750 -28.000	-19.117 -22.203 -25.543 -30.201	-21.432 -24.518 -28.338 -32.997
Segmen b(s,r)	ts(R,S) R10	s 9 2	. 1	0
r 3 2 1	-21.432 -24.518 -28.338 -32.997	-23.746 -26.833 -31.133 -35.792	-26.637 -30.245 -34.247 -39.197	-30.245 -33.853 -38.207 -43.157
Segmen b(s,r)		S10 2	1	. 0
r 3 2 1 0	-30.245 -33.853 -38.207 -43.157	-33.853 -37.461 -42.167 -47.117	-38.207 -42.167 -47.115 -51.668	-43.157 -47.117 -51.668 -56.222

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## EUROPEAN SEARCH REPORT

Application Number

EP 88 10 4102

	DOCUMENTS CONSTR	EDED TO DE DEL EVAN	(TP	
		ERED TO BE RELEVAN		
Category	Citation of document with ind of relevant pass		Relevant to claim	CLASSIFICATION OF THE APPLICATION (Int. Cl. 4)
A	JOURNAL OF THE ILLUM SOCIETY, vol. 2, no. pages 36-42, Illumin Society, New York, U. al.: "Computer designation with faceted representations and the second	1, October 1972, ating Engineering S; R.J.DONOHUE et n of automotive	1-28	F 21 M 3/08
A	US-A-4 495 552 (GRA * Column 2, lines 3-	FF) 17 *	1-28	* .
Α	US-A-4 481 563 (SNY) * Column 2, lines 8-		1-28	
				TECHNICAL FIELDS SEARCHED (Int. Cl.4)
				F 21 M
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	The present search report has bee	n drawn up for all claims	-	
	Place of search	Date of completion of the search		Examiner
TH	E HAGUE	14-06-1988	FOUC	CRAY R.B.F.
Y : pai doc A : tec	CATEGORY OF CITED DOCUMENT ticularly relevant if taken alone ticularly relevant if combined with anoth cument of the same category hnological background	E : earlier patent of after the filing per D : document cited L : document cited	ocument, but publ date I in the application for other reasons	ished on, or
Y: pai doc A: tec O: no	ticularly relevant if combined with anoth cument of the same category	per D : document cited L : document cited	in the application for other reasons	•••••